HIGH-SPEED 1K x 8 DUAL-PORT STATIC RAM

IDT7130SA/LA IDT7140SA/LA

FEATURES

· High-speed access

—Military: 25/35/55/100ns (max.)—Commercial: 25/35/55/100ns (max.)

-Commercial: 20ns 7130 in PLCC and TQFP

Low-power operation
 —IDT7130/IDT7140SA
 Active: 550mW (typ.)
 Standby: 5mW (typ.)
 —IDT7130/IDT7140LA

Active: 550mW (typ.) Standby: 1mW (typ.)

 MASTER IDT7130 easily expands data bus width to 16-or-more-bits using SLAVE IDT7140

• On-chip port arbitration logic (IDT7130 Only)

• BUSY output flag on IDT7130; BUSY input on IDT7140

• Interrupt flags for port-to-port communication

Fully asynchronous operation from either port

• Battery backup operation–2V data retention (LA only)

TTL-compatible, single 5V ±10% power supply

· Military product compliant to MIL-STD-883, Class B

Standard Military Drawing #5962-86875

Industrial temperature range (-40°C to +85°C) is available, tested to military electrical specifications

DESCRIPTION

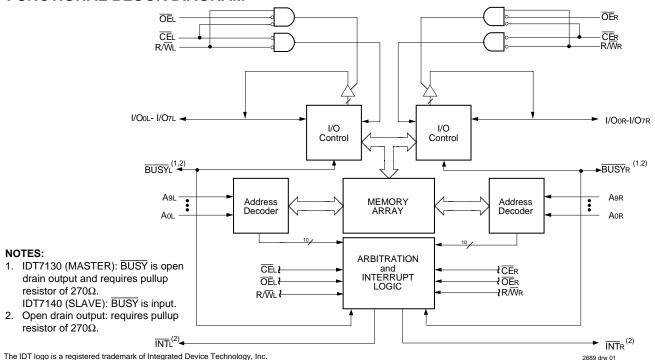
The IDT7130/IDT7140 are high-speed 1K x 8 Dual-Port Static RAMs. The IDT7130 is designed to be used as a stand-alone 8-bit Dual-Port RAM or as a "MASTER" Dual-Port RAM together with the IDT7140 "SLAVE" Dual-Port in 16-bit-or-more word width systems. Using the IDT MASTER/SLAVE Dual-Port RAM approach in 16-or-more-bit memory system applications results in full-speed, error-free operation without the need for additional discrete logic.

Both devices provide two independent ports with separate control, address, and I/O pins that permit independent asynchronous access for reads or writes to any location in memory. An automatic power down feature, controlled by $\overline{\text{CE}}$, permits the on chip circuitry of each port to enter a very low standby power mode.

Fabricated using IDT's CMOS high-performance technology, these devices typically operate on only 550mW of power. Low-power (LA) versions offer battery backup data retention capability, with each Dual-Port typically consuming 200 μ W from a 2V battery.

The IDT7130/IDT7140 devices are packaged in 48-pin sidebraze or plastic DIPs, LCCs, or flatpacks, 52-pin PLCC, and 64-pin TQFP and STQFP. Military grade product is manufactured in compliance with the latest revision of MIL-STD-883, Class B, making it ideally suited to military temperature applications demanding the highest level of performance and reliability.

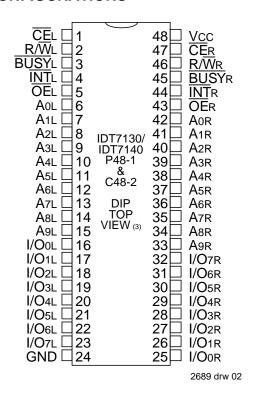
FUNCTIONAL BLOCK DIAGRAM

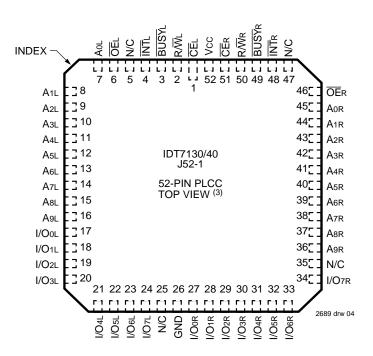


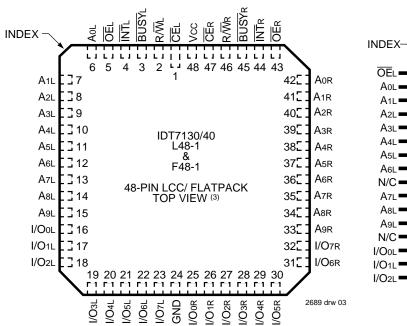
MILITARY AND COMMERCIAL TEMPERATURE RANGES

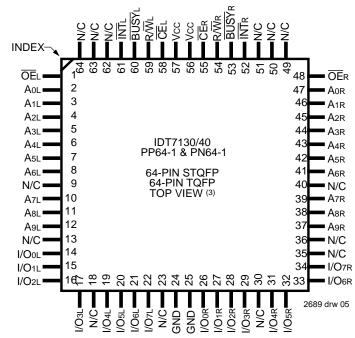
OCTOBER 1996

PIN CONFIGURATIONS (1,2)









NOTES:

- 1. All Vcc pins must be connected to the power supply.
- 2. All GND pins must be connected to the ground supply.
- 3. This text does not indicate orientation of the actual part-marking.

6.01 2

ABSOLUTE MAXIMUM RATINGS(1)

| Symbol | Rating | Commercial | Military | Unit |
|----------------------|--------------------------------------|--------------|--------------|------|
| VTERM ⁽²⁾ | Terminal Voltage with Respect to GND | -0.5 to +7.0 | -0.5 to +7.0 | > |
| ТА | Operating Temperature | 0 to +70 | -55 to +125 | °C |
| TBIAS | Temperature Under Bias | -55 to +125 | -65 to +135 | °C |
| Tstg | Storage Temperature | -55 to +125 | -65 to +150 | °C |
| Іоит | DC Output Current | 50 | 50 | mA |

NOTES:

- 1. Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
- 2. VTERM must not exceed Vcc + 0.5 for more than 25% of the cycle time or 10ns maximum, and is limited to < 20mA for the period of VTERM > Vcc

RECOMMENDED DC OPERATING CONDITIONS

| Symbol | Parameter | Min. | Тур. | Max. | Unit |
|--------|--------------------|--------------|------|--------------------|------|
| Vcc | Supply Voltage | 4.5 | 5.0 | 5.5 | V |
| GND | Supply Voltage | 0 | 0 | 0 | V |
| VIH | Input High Voltage | 2.2 | _ | 6.0 ⁽²⁾ | V |
| VIL | Input Low Voltage | $-0.5^{(1)}$ | | 0.8 | V |

NOTES:

2689 tbl 01

- 1. VIL (min.) \geq -1.5V for pulse width less than 10ns.
- 2. VTERM must not exceed Vcc + 0.5V.

2689 tbl 02

RECOMMENDED OPERATING TEMPERATURE AND SUPPLY VOLTAGE

| Grade | Ambient Temperature | GND | Vcc |
|------------|------------------------|-----|------------|
| Military | −55°C to +125°C | 0V | 5.0V ± 10% |
| Commercial | 0°C to +70°C | 0V | 5.0V ± 10% |

2689 tbl 03

DC ELECTRICAL CHARACTERISTICS OVER THE **OPERATING TEMPERATURE AND SUPPLY VOLTAGE RANGE (Vcc = 5.0V ± 10%)**

| | | | | • | | | |
|--------|--|---|--------|------|------|------|------|
| | | | 7130 | SA | 713 | 0LA | |
| | | | 7140SA | | 714 | 0LA | |
| Symbol | Parameter | Test Conditions | Min. | Max. | Max. | Max. | Unit |
| lu | Input Leakage Current ⁽¹⁾ | VCC = 5.5V, VIN = 0V to VCC | _ | 10 | _ | 5 | μΑ |
| llo | Output Leakage Current ⁽¹⁾ | $\frac{\text{Vcc} = 5.5\text{V}}{\text{CE}} = \text{ViH}, \text{Vout} = 0\text{V to Vcc}$ | _ | 10 | l | 5 | μΑ |
| Vol | Output Low Voltage (I/O0-I/O7) | IOL = 4mA | _ | 0.4 | _ | 0.4 | V |
| Vol | Open Drain Output Low Voltage (BUSY, INT) | IoL = 16mA | _ | 0.5 | _ | 0.5 | V |
| Vон | Output High Voltage | Iон = -4mA | 2.4 | _ | 2.4 | _ | V |

NOTE:

2689 thl 04

CAPACITANCE(1)

 $(TA = +25^{\circ}C, f = 1.0MHz) TQFP ONLY^{(3)}$

| Symbol | Parameter | Conditions ⁽²⁾ | Max. | Unit |
|--------|--------------------|---------------------------|------|------|
| CIN | Input Capacitance | VIN = 3dV | 9 | рF |
| Соит | Output Capacitance | VIN = 3dV | 10 | pF |

NOTES:

2689 tbl 05

- 1. This parameter is determined by device characterization but is not production tested.
- 3dv references the interpolated capacitance when the input and output signals switch from 0V to 3V or from 3V to 0V.
- 3. 11pF max. for other packages.

^{1.} At Vcc ≤ 2.0V leakages are undefined.

2689 tbl 06

2689 tbl 07

DC ELECTRICAL CHARACTERISTICS OVER THE OPERATING TEMPERATURE AND SUPPLY VOLTAGE RANGE^(1,6) (VCC = $5.0V \pm 10\%$)

| | | | | | 7130 | X20 ⁽²⁾ | | X25 ⁽³⁾ | _ |)X35 | 7130 | | |)X100 | |
|--------|--|---|------|----------------------|-----------------|---------------------|--------------------------|----------------------------|----------------------------|--------------------------|----------------------------|------------------------|--------------------------|--------------------------|------|
| Symbol | Parameter | Test Conditions | Vers | ion | Typ. | Max. | | X25 ⁽³⁾ Max. | | OX35 Max. | 7140 Typ. | X55 Max. | | 0X100 Max. | Unit |
| Icc | Dynamic Operating Current (Both Ports Active) | CEL and CER = VIL, Outputs open, f = fMAX ⁽⁴⁾ | MIL. | SA LA SA LA | - 110 110 | _ 250 200 | 110 110 110 110 | 280 220 220 170 | 110 110 110 110 | 230 170 165 120 | | 190 140 155 | 110 110 110 110 | 190 140 155 110 | mA |
| ISB1 | Standby Current (Both Ports - TTL Level Inputs) | $\overline{\text{CE}}\text{L}$ and $\overline{\text{CE}}\text{R}$ = ViH, $f = f\text{MAX}^{(4)}$ | MIL. | SA LA SA LA | — 30 30 | 65 45 | 30 30 30 30 | 80 60 65 45 | 25 25 25 25 25 | 80 60 65 45 | 20 20 20 20 20 | 65 45 65 35 | 20 20 20 20 | 65 45 55 35 | mA |
| ISB2 | Standby Current (One Port - TTL Level Inputs) | \overline{CE} "A" = VIL and \overline{CE} "B" = VIH (7) Active Port Outputs Open, f = fMAX ⁽⁴⁾ | MIL. | SA LA SA LA | — 65 65 | — 165 125 | 65 65 65 65 | 160 125 150 115 | 50 50 50 50 | 150 115 125 90 | 40 40 40 40 | 125 90 110 75 | 40 40 40 40 | 125 90 110 75 | mA |
| ISB3 | Full Standby Current (Both Ports - All CMOS Level Inputs | $\overline{\text{CE}}\text{L}$ and $\overline{\text{CE}}\text{R} \ge \text{VCC -0.2V},$ $\text{VIN} \ge \text{VCC -0.2V or}$ $\text{VIN} \le 0.2\text{V,f} = 0^{(5)}$ | MIL. | SA LA SA LA | - 1.0 0.2 | 15 5 | 1.0 0.2 1.0 0.2 | 30 10 15 5 | 1.0 0.2 1.0 0.2 | 30 10 15 4 | 1.0 0.2 1.0 0.2 | 30 10 15 4 | 1.0 0.2 1.0 0.2 | 30 10 15 4 | mA |
| ISB4 | Full Standby Current (One Port - All CMOS Level Inputs) | $\begin{tabular}{ c c c c }\hline \hline $\overline{C}\overline{E}^*A^* \leq 0.2V$ and \\\hline $\overline{C}\overline{E}^*B^* \geq VCC$ -0.2V or \\\hline $V\text{IN} \geq VCC$ -0.2V or \\\hline $V\text{IN} \leq 0.2$V$, \\\hline $Active Port Outputs$ \\\hline $Open, f = f\text{Max}^{(4)}$ \\\hline \end{tabular}$ | MIL. | SA LA SA LA | 60 60 | 155 115 | 60 60 60 60 | 155 115 145 105 | 45 45 45 45 | 145 105 110 85 | 40 40 40 40 | 110 85 100 70 | 40 40 40 40 | 110 80 95 70 | mA |

NOTES:

1. 'X' in part numbers indicates power rating (SA or LA).

- 2. Com'l Only, 0°C to +70°C temperature range. PLCC and TQFP packages.
- 3. Not available in DIP packages.
- 4. At f = fMax, address and control lines (except Output Enable) are cycling at the maximum frequency read cycle of 1/tRc, and using "AC TEST CONDITIONS" of input levels of GND to 3V.
- 5. f = 0 means no address or control lines change. Applies only to inputs at CMOS level standby.
- 6. Vcc = 5V, TA=+25°C for Typ and is not production tested. Vcc Dc = 100 mA (Typ.)
- 7. Port "A" may be either left or right port. Port "B" is opposite from port "A".

DATA RETENTION CHARACTERISTICS (LA Version Only)

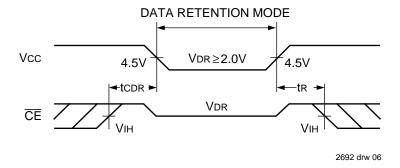
| Symbol | Parameter | Test Conditions | IDT7130 Min. | Unit | | | |
|---------------------|------------------------|--|-----------------|--------------------|-----|------|----|
| Vdr | Vcc for Data Retention | | | 2.0 | _ | _ | V |
| ICCDR | Data Retention Current | | Mil. | _ | 100 | 4000 | μΑ |
| | | $VCC = 2.0V, \overline{CE} \ge VCC - 0.2V$ | Com'l. | _ | 100 | 1500 | μΑ |
| tcdr ⁽³⁾ | Chip Deselect to Data | \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\ | | 0 | _ | _ | ns |
| | Retention Time | $VIN \ge VCC -0.2V \text{ or } VIN \le 0.2V$ | | | | | |
| tR ⁽³⁾ | Operation Recovery | | | tRC ⁽²⁾ | _ | _ | ns |
| | Time | | | | | | |

NOTES:

1. Vcc = 2V, Ta = +25°C, and is not production tested.

- 2. trc = Read Cycle Time
- 3. This parameter is guaranteed but not production tested.

DATA RETENTION WAVEFORM



AC TEST CONDITIONS

| Input Pulse Levels | GND to 3.0V |
|-------------------------------|---------------------|
| Input Rise/Fall Times | 5ns |
| Input Timing Reference Levels | 1.5V |
| Output Reference Levels | 1.5V |
| Output Load | Figures 1, 2, and 3 |
| | |

2689 tbl 08

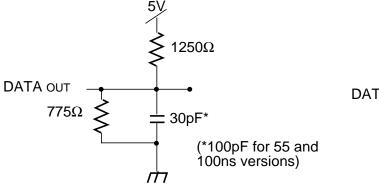


Figure 1. Output Test Load

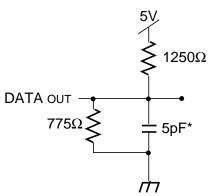
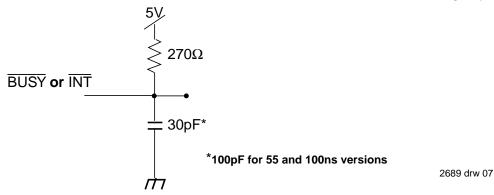


Figure 2. Output Test Load (for thz, tLz, twz, and tow)
* including scope and jig



6.01

Figure 3. BUSY and INT AC Output Test Load

5

AC ELECTRICAL CHARACTERISTICS OVER THE OPERATING TEMPERATURE AND SUPPLY VOLTAGE RANGE⁽³⁾

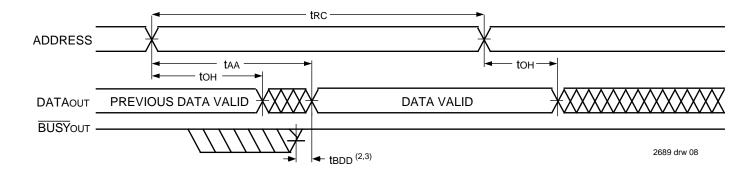
| | | 7130 | | | 7130X25 ⁽⁵⁾ 7140X25 ⁽⁵⁾ | | X35 X35 | 7130X55 7140X55 | | 7130X100 7140X100 | | |
|---------|--|------|------|----|--|----|------------|--------------------|----|----------------------|------|------|
| Symbol | Parameter | Min. | Max. | | Max. | | Max. | | | | Max. | Unit |
| Read Cy | Read Cycle | | | | | | | | | | | • |
| trc | Read Cycle Time | 20 | _ | 25 | _ | 35 | _ | 55 | _ | 100 | _ | ns |
| tAA | Address Access Time | _ | 20 | _ | 25 | | 35 | _ | 55 | | 100 | ns |
| tACE | Chip Enable Access Time | _ | 20 | _ | 25 | _ | 35 | _ | 55 | _ | 100 | ns |
| tAOE | Output Enable Access Time | | 11 | | 12 | _ | 20 | _ | 25 | _ | 40 | ns |
| tон | Output Hold From Address Change | 3 | _ | 3 | _ | 3 | - | 3 | _ | 10 | _ | ns |
| tLZ | Output Low-Z Time ^(1,4) | 0 | _ | 0 | _ | 0 | _ | 5 | _ | 5 | _ | ns |
| tHZ | Output High-Z Time ^(1,4) | _ | 10 | _ | 10 | 1 | 15 | _ | 25 | | 40 | ns |
| tpu | Chip Enable to Power Up Time ⁽⁴⁾ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | ns |
| tPD | Chip Disable to Power Down Time ⁽⁴⁾ | _ | 20 | _ | 25 | _ | 35 | _ | 50 | _ | 50 | ns |

NOTES:

2689 tbl 09

- 1. Transition is measured ±500mV from Low or High-impedance voltage Output Test Load (Figure 2).
- 2. Com'l Only, 0°C to +70°C temperature range. PLCC and TQFP package.
- 3. "X" in part numbers indicates power rating (SA or LA).
- 4. This parameter is guaranteed by device characterization, but is not production tested.
- 5. Not available in DIP packages.

TIMING WAVEFORM OF READ CYCLE NO. 1, EITHER SIDE(1)

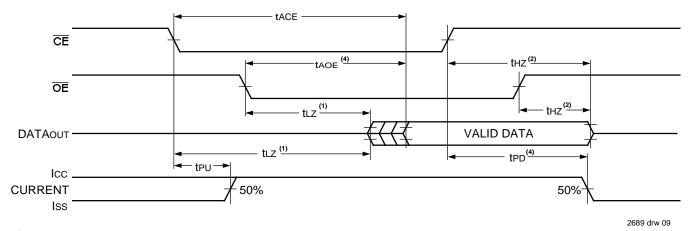


NOTES:

- 1. $R\overline{W} = V_{IH}$, $\overline{CE} = V_{IL}$, and is $\overline{OE} = V_{IL}$. Address is valid prior to the coincidental with \overline{CE} transition Low.
- 2. tbdd delay is required only in the case where the opposite port is completing a write operation to the same the address location. For simultaneous read operations, BUSY has no relationship to valid output data.
- 3. Start of valid data depends on which timing becomes effective last tAOE, tACE, tAA, and tBDD.

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TIMING WAVEFORM OF READ CYCLE NO. 2, EITHER SIDE(3)



NOTES:

- 1. Timing depends on which signal is asserted last, $\overline{\text{OE}}$ or $\overline{\text{CE}}$.
- 2. Timing depends on which signal is deaserted first, OE or CE.
- 3. $R/\overline{W} = VIH$ and the address is valid prior to or coincidental with \overline{CE} transition Low.
- 4. Start of valid data depends on which timing becomes effective last tAOE, tACE, tAA, and tBDD.

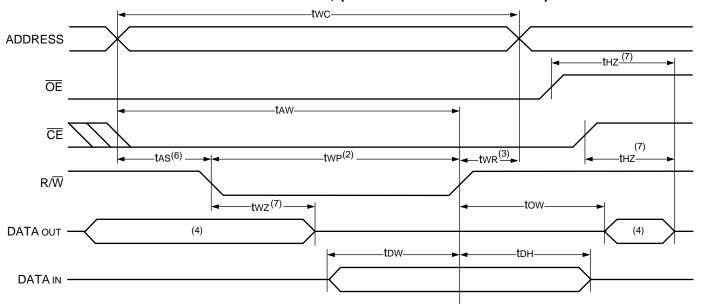
AC ELECTRICAL CHARACTERISTICS OVER THE OPERATING TEMPERATURE AND SUPPLY VOLTAGE RANGE⁽⁵⁾

| | | 7130 | | | (25 ⁽⁶⁾ | 7130 | X35 | 7130 | X55 | 7130X100 | | |
|----------|--|------|------|-------|--------------------|------------------------|------|---------|------|----------|------|------|
| | | | | 7140> | (25 ⁽⁶⁾ | ⁽⁶⁾ 7140X35 | | 7140X55 | | 7140X100 | | |
| Symbol | Parameter | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Unit |
| Write Cy | cle | | | | | | | | | | | |
| twc | Write Cycle Time ⁽³⁾ | 20 | _ | 25 | _ | 35 | _ | 55 | | 100 | 1 | ns |
| tEW | Chip Enable to End-of-Write | 15 | _ | 20 | _ | 30 | _ | 40 | _ | 90 | _ | ns |
| taw | Address Valid to End-of-Write | 15 | _ | 20 | _ | 30 | _ | 40 | _ | 90 | _ | ns |
| tas | Address Set-up Time | 0 | _ | 0 | _ | 0 | _ | 0 | | 0 | | ns |
| twp | Write Pulse Width ⁽⁴⁾ | 15 | _ | 15 | _ | 25 | _ | 30 | _ | 55 | | ns |
| twr | Write Recovery Time | 0 | _ | 0 | _ | 0 | _ | 0 | _ | 0 | | ns |
| tow | Data Valid to End-of-Write | 10 | _ | 12 | _ | 15 | _ | 20 | _ | 40 | _ | ns |
| tHZ | Output High-Z Time ⁽¹⁾ | _ | 10 | I — | 10 | _ | 15 | _ | 25 | _ | 40 | ns |
| tDH | Data Hold Time | 0 | _ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | ns |
| twz | Write Enabled to Output in High-Z ⁽¹⁾ | | 10 | | 10 | | 15 | | 25 | | 40 | ns |
| tow | Output Active From End-of-Write ⁽¹⁾ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | 0 | | ns |

NOTES:

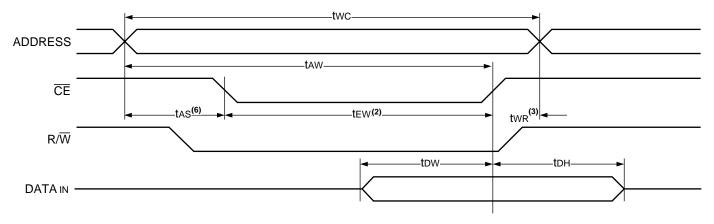
- 2689 tbl 10
- Transition is measured ±500mV from Low or High-impedance voltage with Output Test Load (Figure 2). This parameter is guaranteed by device characterization but is not production tested.
- 2. 0°C to +70°C temperature range only, PLCC and TQFP packages.
- 3. For MASTER/SLAVE combination, two = tbaa + twp, since $R/\overline{W} = V_{IL}$ must occur after tbaa.
- 4. If \overline{OE} is low during a $R\overline{W}$ controlled write cycle, the write pulse width must be the larger of twp or (twz + tow) to allow the I/O drivers to turn off data to be placed on the bus for the required tow. If \overline{OE} is High during a $R\overline{W}$ controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified twp.
- 5. "X" in part numbers indicates power rating (SA or LA).
- 6. Not available in DIP packages.

TIMING WAVEFORM OF WRITE CYCLE NO. 1, $(R/\overline{W}$ CONTROLLED TIMING) $^{(1,5,8)}$



2689 drw 10

TIMING WAVEFORM OF WRITE CYCLE NO. 2, (CE CONTROLLED TIMING)(1,5)



2689 drw 11

NOTES:

- 1. R/\overline{W} or \overline{CE} must be High during all address transitions.
- 2. A write occurs during the overlap (tew or twp) of $\overline{CE} = VIL$ and $R/\overline{W} = VIL$.
- 3. twn is measured from the earlier of \overline{CE} or R/\overline{W} going High to the end of the write cycle.
- 4. During this period, the I/O pins are in the output state and input signals must not be applied.
- 5. If the CE Low transition occurs simultaneously with or after the R/W Low transition, the outputs remain in the High-impedance state.
- 6. Timing depends on which enable signal ($\overline{\text{CE}}$ or R/\overline{W}) is asserted last.
- 7. This parameter is determined be device characterization, but is not production tested. Transition is measured +/- 500mV from steady state with the Output Test Load (Figure 2).
- 8. If \overline{OE} is low during a R/W controlled write cycle, the write pulse width must be the larger of twp or (twz + tow) to allow the I/O drivers to turn off and data to be placed on the bus for the required tow. If \overline{OE} is High during a R/W controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified twp.

AC ELECTRICAL CHARACTERISTICS OVER THE OPERATING TEMPERATURE AND SUPPLY VOLTAGE RANGE⁽⁷⁾

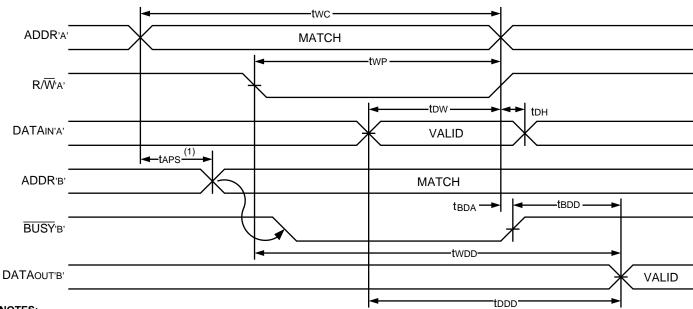
| | | 7130 | X20 ⁽¹⁾ | 7130 | X25 ⁽⁹⁾ | 7130 | X35 | 7130 | X55 | 7130 | X100 | |
|--------|--|------|--------------------|------------------------|--------------------|------|------|---------|------|----------|------|------|
| | | | | 7140X25 ⁽⁹⁾ | | 7140 | X35 | 7140X55 | | 7140X100 | | |
| Symbol | Parameter | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Unit |
| Busy 1 | Fiming (For Master IDT7130 Only) | | _ | | | | | | | | | |
| tBAA | BUSY Access Time from Address | _ | 20 | _ | 20 | _ | 20 | _ | 30 | _ | 50 | ns |
| tBDA | BUSY Disable Time from Address | _ | 20 | _ | 20 | _ | 20 | _ | 30 | _ | 50 | ns |
| tBAC | BUSY Access Time from Chip Enable | _ | 20 | _ | 20 | _ | 20 | _ | 30 | _ | 50 | ns |
| tBDC | BUSY Disable Time from Chip Enable | _ | 20 | _ | 20 | | 20 | _ | 30 | _ | 50 | ns |
| twH | Write Hold After BUSY ⁽⁶⁾ | 12 | _ | 15 | _ | 20 | _ | 20 | _ | 20 | _ | ns |
| twdd | Write Pulse to Data Delay ⁽²⁾ | _ | 40 | _ | 50 | _ | 60 | _ | 80 | _ | 120 | ns |
| tDDD | Write Data Valid to Read Data Delay ⁽²⁾ | _ | 30 | _ | 35 | _ | 35 | _ | 55 | _ | 100 | ns |
| taps | Arbitration Priority Set-up Time ⁽³⁾ | 5 | _ | 5 | _ | 5 | _ | 5 | _ | 5 | _ | ns |
| tBDD | BUSY Disable to Valid Data ⁽⁴⁾ | _ | 25 | _ | 35 | _ | 35 | _ | 50 | _ | 65 | ns |
| Busy T | iming (For Slave IDT7140 Only) | | | | | | | | | | | |
| twB | Write to BUSY Input ⁽⁵⁾ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | ns |
| twH | Write Hold After BUSY ⁽⁶⁾ | 12 | _ | 15 | _ | 20 | _ | 20 | _ | 20 | _ | ns |
| twdd | Write Pulse to Data Delay ⁽²⁾ | _ | 40 | _ | 50 | _ | 60 | _ | 80 | _ | 120 | ns |
| tDDD | Write Data Valid to Read Data Delay(2) | _ | 30 | - | 35 | _ | 35 | _ | 55 | _ | 100 | ns |

NOTES:

2689 tbl 11

- 1. Com'l Only, 0°C to +70°C temperature range. PLCC and TQFP packages only.
- 2. Port-to-port delay through RAM cells from the writing port to the reading port, refer to "Timing Waveform of Write with Port-to-Port Read and BUSY."
- 3. To ensure that the earlier of the two ports wins.
- 4. tbdd is a calculated parameter and is the greater of 0, twbd twp (actual), or tbdd tbw (actual).
- 5. To ensure that a write cycle is inhibited on port 'B' during contention on port 'A'.
- 6. To ensure that a write cycle is completed on port 'B' after contention on port 'A'.
- 7. "X" in part numbers indicates power rating (SA or LA).
- 8. Not available in DIP packages.

TIMING WAVEFORM OF WRITE WITH PORT-TO-PORT READ AND BUSY (2.3,4)



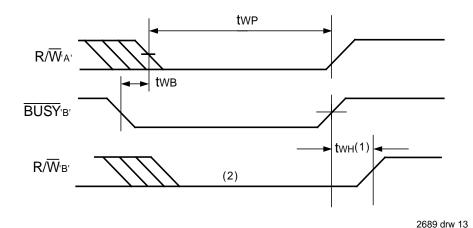
NOTES:

- 1. To ensure that the earlier of the two ports wins. tBDD is ignored for slave (IDT7140).
- 2. $\overline{CE}L = \overline{CE}R = VIL$.

2689 drw 12

- 3. $OE = V_{IL}$ for the reading port.
- 4. All timing is the same for the left and right ports. Port 'A' may be either the left or right port. Port "B" is opposite from port "A".

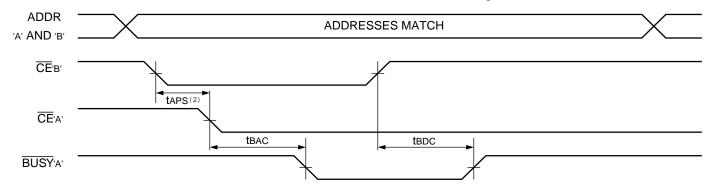
TIMING WAVEFORM OF WRITE WITH BUSY(3)



NOTES:

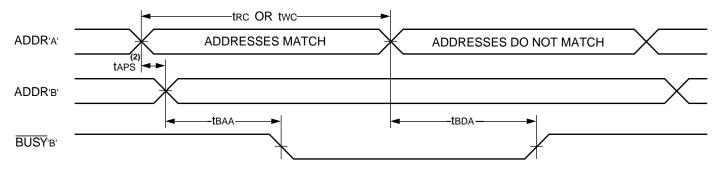
- 1. twn must be met for both BUSY Input (IDT7140, slave) or Output (IDT7130 master).
- 2. BUSY is asserted on port 'B' blocking R/W'B', until BUSY'B' goes High.
- All timing is the same for the left and right ports. Port 'A' may be either the left or right port. Port "B" is opposite from port "A".

TIMING WAVEFORM OF BUSY ARBITRATION CONTROLLED BY CE TIMING (1)



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TIMING WAVEFORM OF BUSY ARBITRATION CONTROLLED BY ADDRESS MATCH TIMING (1)



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NOTES:

- 1. All timing is the same for left and right ports. Port "A" may be either left or right port. Port "B" is the opposite from port "A".
- 2. If tAPS is not satisified, the BUSY will be asserted on one side or the other, but there is no guarantee on which side BUSY will be asserted (7130 only).

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AC ELECTRICAL CHARACTERISTICS OVER THE OPERATING TEMPERATURE AND SUPPLY VOLTAGE RANGE⁽²⁾

| | | 7130> | (20 ⁽¹⁾ | 7130X25 ⁽³⁾ 7140X25 ⁽³⁾ | | 7130X35 7140X35 | | 7130X55 7140X55 | | 7130X100 7140X100 | | |
|------------------|----------------------|-------|--------------------|--|------|--------------------|------|--------------------|------|----------------------|------|------|
| Symbol | Parameter | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Unit |
| Interrupt Timing | | | | | | | | | | | | |
| tas | Address Set-up Time | 0 | _ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | ns |
| twr | Write Recovery Time | 0 | _ | 0 | _ | 0 | _ | 0 | _ | 0 | _ | ns |
| tins | Interrupt Set Time | _ | 20 | _ | 25 | _ | 25 | _ | 45 | _ | 60 | ns |
| tinr | Interrupt Reset Time | _ | 20 | _ | 25 | _ | 25 | _ | 45 | _ | 60 | ns |

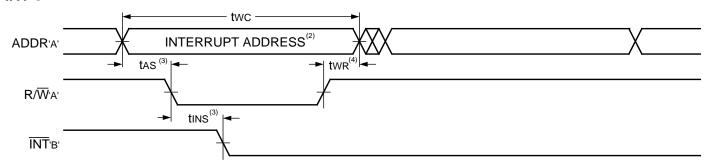
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NOTES:

- 0°C to +70°C temperature range only, PLCC and TQFP packages.
- "X" in part numbers indicates power rating (SA or LA).
- Not available in DIP packages .

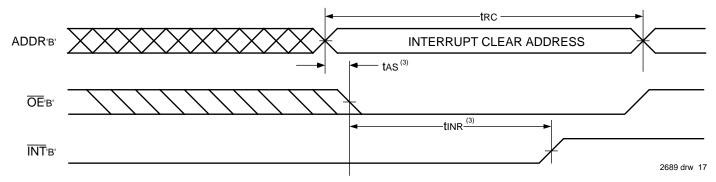
TIMING WAVEFORM OF INTERRUPT MODE

INT SET:



INT CLEAR:





NOTES:.

- 1. All timing is the same for left and right ports. Port "A" may be either left or right port. Port "B" is the opposite from port "A".
- 2. See Interrupt Truth Table.
- Timing depends on which enable signal (CE or R/W) is asserted last.
 Timing depends on which enable signal (CE or R/W) is de-asserted first.

TRUTH TABLES

TABLE I — NON-CONTENTION READ/WRITE CONTROL⁽⁴⁾

| Left or Right Port(1) | | | | |
|-----------------------|---|---|---------|---|
| R/W | E | Е | D0-7 | Function |
| Х | Н | Χ | Z | Port Disabled and in Power- |
| | | | | Down Mode, ISB2 or ISB4 |
| Х | Н | Х | Z | $\overline{CE}R = \overline{CE}L = VIH, Power-Down$ |
| | | | | Mode, ISB1 or ISB3 |
| L | L | Χ | DATAIN | Data on Port Written Into Memory (2) |
| Н | Ĺ | L | DATAOUT | Data in Memory Output on Port ⁽³⁾ |
| Н | L | Н | Z | High Impedance Outputs |

NOTES:

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- 1. $A0L A10L \neq A0R A10R$.
- 2. If $\overline{BUSY} = L$, data is not written.
- 3. If BUSY = L, data may not be valid, see twop and tood timing.
- 4. 'H' = VIH, 'L' = VIL, 'X' = DON'T CARE, 'Z' = HIGH IMPEDANCE

TABLE II — INTERRUPT FLAG(1,4)

| Left Port | | | | Right Port | | | | | | |
|-----------|-----|-----|-----------|------------------|------|-----|-----|-----------|------------------|-----------------------|
| R/WL | CEL | ŌĒL | A9L - A0L | ĪNT∟ | R/WR | CER | ŌĒR | A9L - A0R | ĪNTR | Function |
| L | L | Х | 3FF | Х | Х | Х | Х | Χ | L ⁽²⁾ | Set Right INTR Flag |
| Х | Х | Х | Х | Х | Х | L | L | 3FF | H ⁽³⁾ | Reset Right INTR Flag |
| Х | Х | X | Х | L ⁽³⁾ | L | L | Х | 3FE | Х | Set Left INTL Flag |
| Х | L | L | 3FE | H ⁽²⁾ | Х | Х | Х | Х | Х | Reset Left INTL Flag |

NOTES:

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- 1. Assumes $\overline{BUSY}L = \overline{BUSY}R = VIH$
- 2. If $\overline{BUSY}L = V_{IL}$, then No Change.
- 3. If $\overline{BUSYR} = V_{IL}$, then No Change.
- 4. 'H' = HIGH,' L' = LOW,' X' = DON'T CARE

TABLE III — ADDRESS BUSY ARBITRATION

| | Inp | uts | Out | puts | |
|-----|-------------|--------------------|-----------------------|-----------------------|------------------------------|
| CEL | <u>CE</u> R | A0L-A9L A0R-A9R | BUSY _L (1) | BUSY _R (1) | Function |
| Х | Х | NO MATCH | Н | Н | Normal |
| Н | Х | MATCH | Н | Н | Normal |
| Х | Н | MATCH | Н | Н | Normal |
| L | L | MATCH | (2) | (2) | Write Inhibit ⁽³⁾ |

NOTES:

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- Pins BUSYL and BUSYR are both outputs for IDT7130 (master). Both are inputs for IDT7140 (slave). BUSYx outputs on the IDT7130 are open drain, not push-pull outputs. On slaves the BUSYx input internally inhibits writes.
- 'L' if the inputs to the opposite port were stable prior to the address and enable inputs of this port. 'H' if the inputs to the opposite port became stable after the address and enable inputs of this port. If tAPS is not met, either BUSYL or BUSYR = Low will result. BUSYL and BUSYR outputs can not be low simultaneously.
- Writes to the left port are internally ignored when BUSYL outputs are driving Low regardless of actual logic level on the pin. Writes to the right port are internally ignored when BUSYR outputs are driving Low regardless of actual logic level on the pin.

FUNCTIONAL DESCRIPTION

The IDT7130/IDT7140 provides two ports with separate control, address and I/O pins that permit independent access for reads or writes to any location in memory. The IDT7130/IDT7140 has an automatic power down feature controlled by $\overline{\text{CE}}$. The $\overline{\text{CE}}$ controls on-chip power down circuitry that permits the respective port to go into a standby mode when not selected ($\overline{\text{CE}} = V_{\text{IH}}$). When a port is enabled, access to the entire memory array is permitted.

INTERRUPTS

If the user chooses to use the interrupt function, a memory location (mail box or message center) is assigned to each port. The left port interrupt flag (\overline{INTL}) is asserted when the right port writes to memory location 3FE (HEX), where a write is defined as the $\overline{CE} = R/\overline{W} = V_{IL}$ per the Truth Table. The left port clears the interrupt by access address location 3FE access when $\overline{CER} = \overline{OER} = V_{IL}$, R/\overline{W} is a "don't care". Likewise, the right port interrupt flag (\overline{INTR}) is asserted when the left port writes to memory location 3FF (HEX) and to clear the interrupt flag (\overline{INTR}), the right port must access the memory location 3FF. The message (8 bits) at 3FE or 3FF is user-defined, since it is an addressable SRAM location. If the interrupt function is not used, address locations 3FE and 3FF are not used as mail boxes, but as part of the random access memory. Refer to Table II for the interrupt operation.

BUSY LOGIC

Busy Logic provides a hardware indication that both ports of the RAM have accessed the same location at the same time. It also allows one of the two accesses to proceed and signals the other side that the RAM is "Busy". The Busy pin can then be used to stall the access until the operation on the other side is completed. If a write operation has been attempted from the side that receives a busy indication, the write signal is gated internally to prevent the write from proceeding.

The use of busy logic is not required or desirable for all applications. In some cases it may be useful to logically OR the busy outputs together and use any busy indication as an interrupt source to flag the event of an illegal or illogical operation. In slave mode the BUSY pin operates solely as a write inhibit input pin. Normal operation can be programmed by tying the BUSY pins High. If desired, unintended write operations can be prevented to a port by tying the Busy pin for that port Low.

The Busy outputs on the IDT7130 RAM (Master) are open drain type outputs and require open drain resistors to operate. If these RAMs are being expanded in depth, then the Busy indication for the resulting array does not require the use of an external AND gate.

WIDTH EXPANSION WITH BUSY LOGIC MASTER/SLAVE ARRAYS

When expanding an RAM array in width while using busy logic, one master part is used to decide which side of the RAM array will receive a busy indication, and to output that indication. Any number of slaves to be addressed in the same address range as the master, use the busy signal as a write inhibit signal. Thus on the IDT7130/IDT7140 RAMs the Busy pin is an output if the part is Master (IDT7130), and the Busy pin is an input if the part is a Slave (IDT7140) as shown in Figure 4.

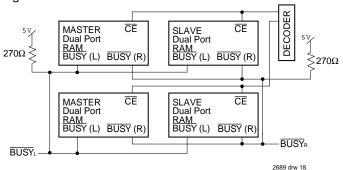
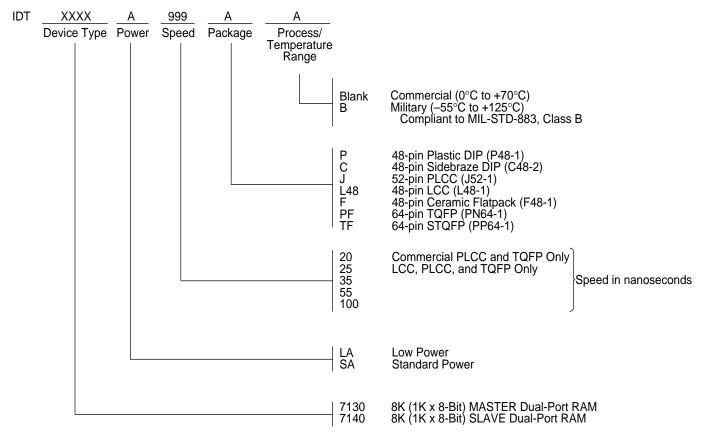


Figure 4. Busy and chip enable routing for both width and depth expansion with IDT7130 (Master) and IDT7140 (Slave) RAMs.

If two or more master parts were used when expanding in width, a split decision could result with one master indicating busy on one side of the array and another master indicating busy on one other side of the array. This would inhibit the write operations from one port for part of a word and inhibit the write operations from the other port for the other part of the word.

The Busy arbitration, on a Master, is based on the chip enable and address signals only. It ignores whether an access is a read or write. In a master/slave array, both address and chip enable must be valid long enough for a busy flag to be output from the master before the actual write pulse can be initiated with either the R/\overline{W} signal or the byte enables. Failure to observe this timing can result in a glitched internal write inhibit signal and corrupted data in the slave.

ORDERING INFORMATION



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