## Esterlıne̊e (Powe systems

Featuring LEACH ${ }^{\circledR}$ Products

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## Esterline Power Systems

## LEACH ${ }^{\circledR}$ Products are Recognized for their Design Excellence, Quality \& Reliability

As one of the core capabilities of Esterline Technologies Corporation, Esterline Power Systems draws upon the rich aerospace and military heritage of LEACH ${ }^{\circledR}$. The LEACH Relay Co. introduced the first "break-in" relay in 1919, and further developed the art of power switching technology throughout the 20th century.

Today, LEACH ${ }^{\circledR}$ products include: the balanced armature, balanced force relays, rotary \& solenoid contactors, as well as control devices and power management systems, which have been used in the most severe environments in space, aerospace, military, rail, and other high-end applications worldwide.

With its extensive product line, advanced design and engineering processes, more than 1,800 dedicated employees, and representatives in more than 20 countries, Esterline Power Systems continues to maintain its hard-earned position as an industry leader.


First Break-in Relay -1919

## CERTIFICATIONS \& OUALIFICATIONS:

ESA/ESCC
D6-82479
CFR 21
CFR/JAR 145

JAR 21
M83536
QUALIFAS/A
M6106
IRIS (Rail)
M83726
M39016

## GLOBAL OPERATION

Esterline Power Systems has manufacturing facilities in North America, Europe and Asia. Each facility offers unique engineering, manufacturing, sales \& service capabilities, and each function has an integral part of the Esterline Power Systems team. With the industry's finest electrical testing laboratories, combined with state-of-the-art manufacturing, Esterline Power Systems is able to provide world-class service and an ever-expanding product line.


AMERICAS Buena Park, CA • Tijuana, Mexico
EUROPE Sarralbe, France • Niort, France
ASIA Zunyi, China • Hong Kong, China • Bangalore, India
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## LEACH PRODUCT TYPES AND SPECIFICATIONS

## PRODUCT TYPES:

Subminiature Relays (Low level to 75 Amps)
For decades, LEACH ${ }^{\circledR}$ subminiature relays have set the industry standard for technology and reliability. With their proven high performance in the most demanding applications, they are ideal for critical subsea, shipboard, ground-based, space, and aerospace applications.

Balanced Armature Relays (10 Amps to 25 Amps)
LEACH ${ }^{\circledR}$ balanced armature relays have been used in commercial and military aircraft, trucks, buses, ships, and tanks - applications that call for proven durability, high performance and long life. Several terminal mounting styles, dust-resistant, moisture-resistant and hermetically-sealed enclosures. A variety of operating ratings and characteristics are available.

Power Contactors (25 Amps to 700 Amps )
LEACH ${ }^{\circledR}$ power contactors are available with optional auxiliary contacts in sealed and unsealed models. "Smart" programmable contactors and special mounting styles are also available.

Time Delay Relays (150 mAmps to 25 Amps)
LEACH ${ }^{\circledR}$ time delay devices combine the proven capability of industry standard relays with highly reliable hybrid microelectronics timing circuits.

Power Monitors and Sensors (up to 10 Amps)
Designed to meet the requirements of MIL-R-28894, LEACH ${ }^{\circledR}$ power monitors and sensors constantly monitor and protect critical AC or DC circuits.

Solid-state Power Controllers (1 Amp to 220 Amps )
Ideal for applications where reliability is key and size and weight are major concerns; LEACH ${ }^{\circledR}$ SSPCs employ a FET output stage and are constructed using thick-film technology, they are hermetically sealed, and mainly metal enclosures.

## PRODUCT SPECIFICATIONS:

## MIL-PRF-39016

This specification covers relays rated from low level to 2 Amps used primarily in electronic and communication equipment. All relays are Established Reliability (ER), and hermetically-sealed types.

## MIL-PRF-6106

This specification establishes general requirements for electromechanical relays with contact ratings from 25 amperes resistive (unless otherwise specified) and upward for use in electrical applications. Auxiliary contacts may be rated at lower currents. Relays covered by this specification are capable of meeting the electrical and environmental requirements when mounted directly to the structure of aircraft, missile, spacecraft, ship, and other primary vehicles or in ground support and shipboard equipment. Other ratings may be as specified.

## MIL-PRF-83536

This specification covers the general requirements for electromagnetic, hermetically sealed relays for use in aircraft, missile, spacecraft, ship, and other primary vehicles or in ground support equipment. These relays are designed to operate over the full range from low level to power switching with contact ratings up to 25 amperes alternating current (ac) or direct current (dc).

## MIL-PRF-83726

This specification establishes the general requirements for time delay relays that are a combination of hybrid microcircuits, solid state electronics with an integral electromagnetic relay, or solid state output. Relays covered by this specification are intended for use in aerospace and associated ground support electrical and electronic systems and equipment

|  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | E, D | GP2, GP2A, GP250 | W260, F250 | GP5 |
| Rating: | 1 Amp | 2 Amps | 2 Amps | 2 Amps |
| Contact configuration: | 2 PDT | 2 PDT | 2 PDT | 2 PDT |
| Style: | Non-latch and Latch | Non-latch and Latch | Non-latch | Non-latch |
| Designed to: | MIL-PRF-39016 | MIL-PRF-39016 | MIL-PRF-39016 | MIL-PRF-39016 |
| Qualified to: | $\begin{gathered} \text { SCC3601/012 } \\ \text { SCC3602/019 } \\ \text { CECC16101-023 } \\ \text { CECC16101-024 } \end{gathered}$ | $\begin{aligned} & \text { SCC3601/003 } \\ & \text { SCC3602/003 } \\ & \text { SCC3602/010 } \\ & \text { CECC1610/014 } \end{aligned}$ | M39016/6 CECC16101/014 CECC16101/021 | $\begin{gathered} \text { CECC16101/014 } \\ \text { SCC3601/003 } \end{gathered}$ |
| Electrical Data | E, D | GP2, GP2A, GP250 | W260, F250 | GP5 |
| Contact load rating (voltage): | 28 VDC | 28 VDC 115 VAC | 28 VDC 115 VAC | 28 VDC 115 VAC |
| Current (Amps): | - | $60-400 \mathrm{~Hz}$ | 400 Hz | 400 Hz |
| Load Type resistive: | 1 | 20.3 | 20.3 | 2 |
| Inductive: | 0.2 | 0.75 - | 0.75 - | - - |
| Motor: | - |  |  | - - |
| Lamp: | 0.1 | - - | 0.4 | - - |
| Nominal coil voltage(s): | 6-28 VDC | 6-26 VDC | 5-60 VDC | $6-26$ VDC |
| Coil Power | - | - | . | - |
| Nominal: | $0.5 \mathrm{~W} / 0.25 \mathrm{~W}$ | 1 W | 1 W | 1.4 W |
| At pick up: | $0.13 \mathrm{~W} / 0.06 \mathrm{~W}$ | 0.28 W | 0.28 W | 0.28 W |
| Operate time, max. (ms): | 5-6 | 4 | 4 | 4 |
| Environmental Data | E, D | GP2, GP2A, GP250 | W260, F250 | GP5 |
| Sinusoidal vibration (g): | $\begin{aligned} & 30 @ 70-3000 \mathrm{~Hz} \\ & 70 @ 70-2000 \mathrm{~Hz} \end{aligned}$ | $\begin{aligned} & 30 @ 70-3000 \mathrm{~Hz} \\ & 20 @ 70-3000 \mathrm{~Hz} \end{aligned}$ | $\begin{aligned} & 30 @ 70-3000 \mathrm{~Hz} \\ & 20 @ 70-3000 \mathrm{~Hz} \end{aligned}$ | 30 @ 70-2000 Hz |
| Shock (g): | 75-100 | 100 | 50-100 | 100 |
| Temperature range | $-65^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-65^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-65^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-65^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Mechanical Data | E, D | GP2, GP2A, GP250 | W260, F250 | GP5 |
| Weight, max. (oz./grams): | $\begin{gathered} <0.129 \mathrm{oz} . \\ (4 \mathrm{~g} .) \end{gathered}$ | $\begin{gathered} <0.354 \text { oz. } \\ (11 \mathrm{~g} .) \end{gathered}$ | $\begin{gathered} <0.32 \mathrm{oz} . \\ (10 \mathrm{~g} .) \end{gathered}$ | $\begin{gathered} <0.354 \mathrm{oz} . \\ (11 \mathrm{~g} .) \end{gathered}$ |
| Dimensions, max. (in.): (L x W x H) | $0.504 \times 0.236 \times 0.409$ | $0.811 \times 0.413 \times 0.409$ | $1.32 \times 0.90 \times 0.41$ | $0.803 \times 0.409 \times 40$ |
| Sockets available | - | S0508, SO510, SO501 | SF250-R4, HRCW, S09005 | HRCW |
| Mounting styles: | 4 | 8 | 8 | 12 |
| Terminal types: | 4 | 3 | 3 | 3 |

*ESA qualified products also available. Contact factory for details.

## SUBMINIATURE RELAYS (Low level to 10 Amps)

|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | X, XL, XA | Y, YL, YA | XC, XCL | YC, YCL, YCA | F600, F601 |
| Rating: | Low level to 5 Amps | Low level to 5 Amps | Low level to 10 Amps | Low level to 10 Amps | Low level to 10 Amps |
| Contact configuration: | 2 PDT | 4 PDT | 1 PDT | 3 PDT | 6 PDT |
| Style: | Non-latch and Latch | Non-latch and Latch | Non-latch and Latch | Non-latch and Latch | Non-latch |
| Designed to: | XA, XL: MIL-PRF-6106 <br> X: MIL-PRF-83536 | YA, YL: MIL-PRF-6106 <br> Y: MIL-PRF-83536 | MIL-PRF-6106 | YCL, YCA: MIL-PRF-6106 YC: MIL-PRF-83536 | M83536/25, 26 |
| Qualified to: | $\begin{aligned} & \text { X: M83536/1, } 2 \\ & \text { XL: M6106/38 } \end{aligned}$ | Y: M83536/5, 6 <br> YL: M6106/39 |  | $\begin{aligned} & \text { YC: M83536/21, } 22 \\ & \text { YCL: M6106/40 } \end{aligned}$ | CECC16101/020 CECC16303/806 |
| Electrical Data | X, XL, XA | Y, YL, YA | XC, XCL | YC, YCL, YCA | F600, F601 |
| Contact rating (Amps) | - | - | - | - | - |
| @ 28 VDC | - | - | - | - | - |
| Resistive: | 5 | 5 | 10 | 10 | 10 |
| Inductive: | 3 | 3 | 6 | 6 | 8 |
| Motor: | 2 | 2 | 4 | 4 | 4 |
| Lamp: | 1 | 1 | 2 | 2 | 2 |
| @115 VAC, $400 \mathrm{~Hz}, 3 \varnothing$ <br> (Case grounded) | Same as DC rating except inductive is 5 Amps and motor is 3 Amps | Same as DC rating except inductive is 5 Amps and motor is 3 Amps | Same as DC rating except inductive is 10 Amps | Same as DC rating except inductive is 8 Amps | Same as DC rating |
| Nominal coil voltage(s) | - | - | - | - | - |
| DC Non-latch:: | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 12-110 VDC |
| DC Latch: | 6/12/28 VDC | 6/12/28 VDC | 6/12/28 VDC | 6/12/28 VDC | - |
| AC Coil: | $\begin{gathered} 28,115 / 200 \mathrm{VAC} \\ 50-400 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28,115 / 200 \mathrm{VAC} \\ 50-400 \mathrm{~Hz} \end{gathered}$ |  | $\begin{gathered} 28,115 / 200 \text { VAC } \\ 50-400 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28,115 \mathrm{VAC} \\ 60-400 \mathrm{~Hz} \end{gathered}$ |
| Coil resistance(s) (Ohms) | - | - | - | - | - |
| DC Non-latch:: | 30/125/500/1600 | 25/100/400/1275 | 25/125/500/1600 | 25/100/400/1275 | 40-3200 |
| DC Latch: | 43/182/730 | 37/148/600 | 730 | 600 | - |
| AC Coil, Current, I max. | .1001.0401.024 | .1201.0401.028 | - | .1201.0401.028 | - |
| Operate time, max. (ms) | - | - | - | - | - |
| DC Non-latch:: | 4 | 6 | 6 | 6 | 15 |
| DC Latch: | 4 | 6 | 6 | 15 | - |
| AC Coil: | 4 | 5 | - | 15 | 20 |
| Release time, max. (ms) | - | - | - | - | . |
| DC Non-latch:: | 4 | 6 | 6 | 6 | 10 |
| AC Coil: | 4 | 25 | - | 25 | 50 |
| Bounce time, max. (ms): | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| Environmental Data | X, XL, XA | Y, YL, YA | XC, XCL | YC, YCL, YCA | F600, F601 |
| Sinusoidal vibration (g): | 30 @ 70-3000 Hz | 30 @ 70-3000 Hz | 30 @ 70-3000 Hz | 30 @ 70-3000 Hz | 30 @ 75-3000 Hz |
| Shock (g): | 200 | 200 | 200 | 200 | 50 |
| Temperature range | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-65^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Mechanical Data | X, XL, XA | Y, YL, YA | XC, XCL | YC, YCL, YCA | F600, F601 |
| Weight, max. (oz./lbs.): | . 56 oz (16 g.) | 1.06 oz. (30 g.) | . 56 oz. (16 g.) | 1.09 oz. (31 g.) | <3.054 oz. (95 g.) |
| Dimensions, max. (in.): | $0.810 \times 0.410 \times 0.640$ | $0.810 \times 0.810 \times 0.640$ | $0.810 \times 0.410 \times 0.640$ | $0.810 \times 0.810 \times 0.640$ | $1.484 \times 1.024 \times 1.012$ |
| ( $\mathrm{L} \times \mathrm{W} \times \mathrm{H}$ ) | - | - | - | - | - |
| Sockets available |  | - | - | - | - |
| Non-latch DC Coil: | SO-1064-001 | SO-1066-001 | SO-1064-10425 | S0-1065-001 | S600 |
| Latch DC Coil: | SO-1064-003 | SO-1066-003 | SO-1064-10534 | S0-1065-003 | SF600 |
| Non-latch AC Coil: | So-1064-10444 | SO-1066-10385 | - | SO-1065-10392 | S601 |
| 28 VAC Coil: | SO-1064-10445 | SO-1066-10386 | - | SO-1065-10393 | S601 |
| Mounting styles: | 5 | 5 | 5 | 5 | 4 |
| Terminal types: | 4 | 3 | 4 | 3 | 4 |

# SUBMINIATURE RELAYS (Low level to 75 Amps) 

|  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | J, JA, JL | K, KA, KL | JC, JCA, JCL, JS, JSA | KC, KCA, KCL | KD, KDA, KDL | KM, KX, KXD, KXL, KXDL |
| Rating: | Low level to 12 Amps $\ddagger$ | Low level to 12 Amps $\ddagger$ | Low level to 25 Amps | Low level to 25 Amps | Low level to 25 Amps | 50-75 Amps |
| Contact configuration: | 2 PDT | 4 PDT | 1 PDT | 3 PDT | 3 PST/NO, 2 Amps 1 PDT Aux. | 1 PST/DM or DB, 2 Amps 1 PST |
| Style: | Non-latch and Latch | Non-latch and Latch | Non-latch and Latch | Non-latch and Latch | Non-latch and Latch $\dagger$ | Non-latch and Latch |
| Designed to: | MIL-PRF-83536 | MIL-PRF-83536 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | M83536/9, 10, 11, 12, 13 | M83536/15, 16, 17, 18, 19 | JC, JS: M6106/19 JCL: M6106/20 | $\begin{aligned} & \text { KC: M83536/32/33 } \\ & \text { KCL: MS27742 } \end{aligned}$ | KD, KDA: M6106/13 KDL: M6106/12 |  |
| Electrical Data | J, JA, JL | K, KA, KL | JC, JCA, JCL, JS, JSA | KC, KCA, KCL | KD, KDA, KDL | KM, KX, KXD, KXL, KXDL |
| Contact rating (Amps): | - | - | - | - | - | - |
| @ 28 VDC | - | - | - | - | - | - |
| Resistive: | 12 | 12 | $25 \quad 10$ | 25 | 25 | $50 \quad 75$ |
| Inductive: | 8 | 8 | $12 \quad 10$ | 12 | 12 | 1520 |
| Motor: | 4 | 4 | 104 | 10 | 10 | $30 \quad 20$ |
| Lamp: | 2 | 2 | $5 \quad 4$ | 5 | 5 | $15 \quad 10-16$ |
| @ 115/220 VAC, $400 \mathrm{~Hz}, 3 \varnothing$ : (Case grounded) | Same as DC rating except resistive is 10 Amps | Same as DC rating except resistive is 10 Amps | $\begin{aligned} \text { Same as } & n / a \\ \text { DC rating } & \text { See note ** } \end{aligned}$ | Same as DC rating except inductive is 15 Amps | Same as DC rating except inductive is 15 Amps | See note $\dagger \dagger$ n/a |
| Nominal coil voltage(s): | - | - | - | - | - | - |
| DC Non-latch: | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28 VDC 28 VDC |
| DC Latch: | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28/48 VDC | 6/12/28 VDC 28 VDC |
| AC Coil: | $\begin{gathered} 28,115 / 200 \mathrm{VAC} \\ 50-400 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28,115 / 200 \text { VAC } \\ 50-400 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28,115 / 200 \text { VAC } \\ 50-400 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28,115 / 200 \mathrm{VAC} \\ 50-400 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28,115 / 200 \mathrm{VAC} \\ 50-400 \mathrm{~Hz} \end{gathered}$ | - - |
| Coil resistance(s) (Ohms) | - | - | - | - | - | - |
| DC Non-latch: | 20/80/320/1000 | 18/70/290/890 | 20/80/320/1000 | 18/70/290/890 | 18/70/290/890 | 18/70/290 290 |
| DC Latch: | 38/150/600/1600 | 28/112/450/1500 | 38/150/600/1600 | 28/112/450/1500 | 28/112/450/1500 | 28/112/450 450 |
| AC Coil, Current, I max.: | .2401.040\%.024 | .1201.0401.028 | .100\%.040\%.024 | .120\%.040\%.028 | .1201.0401.028 | - 120 |
| Operate time, max. (ms) | - | - | - | - | - | - |
| DC Non-latch: | 10 | 15 | 10 | 15 | 15 | 15 |
| DC Latch: | 10 | 15 | 10 | 15 | 15 | 15 |
| AC Coil: | 15 | 20 | 15 | 20 | 20 | - |
| Release time, max. (ms) | - | - | - | - | - | - |
| DC Non-latch: | 10 | 15 | 10 | 15 | 15 | 15 |
| AC Coil: | 50 | 50 | 50 | 50 | 50 | . |
| Bounce time, max. (ms): | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 (Aux. 4) | 1.01 .0 (Aux. 4) |
| Environmental Data | J, JA, JL | K, KA, KL | JC, JCA, JCL, JS, JSA | KC, KCA, KCL | KD, KDA, KDL | KM, KX, KXD, KXL |
| Sinusoidal vibration (g): | 30 @ 70-3000 Hz | 30 @ 70-3000 Hz | $30 @ 70-3000 \mathrm{~Hz}$ | 30 @ 70-3000 Hz | 30 @ 70-3000 Hz | $\begin{aligned} & 30 @ 70-3000 \mathrm{~Hz} \\ & 20 @ 70-3000 \mathrm{~Hz} \end{aligned}$ |
| Shock (g): | - | - | - | - | - | - |
| Temperature range | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Mechanical Data | J, JA, JL | K, KA, KL | JC, JCA, JCL, JS, JSA | KC, KCA, KCL | KD, KDA, KDL | KM, KX, KXD, KXL |
| Weight, max. (oz./grams): | 1.4 oz. (40 g.) | $\begin{aligned} & \text { DC: } 2.5 \text { oz. (71 g.) } \\ & \text { AC: } 2.7 \text { oz. (77 g.) } \end{aligned}$ | $1.6 \mathrm{oz}$. ( 45 g .) | 3.0 oz. (85 g.) | 3.0 oz. (85 g.) | 3.0 oz. (85 g.) |
| Dimensions, max. (in.): (L x W x H) | $\begin{aligned} & \text { DC: } 1.025 \times 0.525 \times 1.010 \\ & \text { AC: } 1.025 \times 0.525 \times 1.125 \end{aligned}$ | $1.025 \times 0.025 \times 1.010$ | $\begin{aligned} & \text { DC: } 1.015 \times 0.515 \times 1.000 \\ & \text { AC: } 1.015 \times 0.515 \times 1.125 \end{aligned}$ | $1.025 \times 1.025 \times 1.010$ | $1.025 \times 1.025 \times 1.010$ | $1.025 \times 1.025 \times 1.70$ |
| Sockets available | - | - | - | - | - | - |
| Non-latch DC Coil: | SO-1049-8309 | SO-1048-8308 | SO-1063-9033 | SO-1057-8912 | SO-1059-8914 | - |
| Latch DC Coil: | SO-1055-8690 | SO-1056-8691 | SO-1063-9036 | SO-1058-8913 | SO-1060-8915 | - |
| Non-latch AC Coil: | SO-1049-8772 | SO-1048-8776 | SO-1063-9034 | SO-1062-8917 | SO-1061-8916 | - |
| 28 VAC Coil: | SO-1055-8774 | SO-1048-8779 | - | - | - | - |
| JC, JCA \& JCL @ 50 ADC \& 8 Same design as KC series wi MIL-PRF-83536 rated at 10 Am | 0 Amp 400 Hz overload. hadded auxiliary pole. | **JS/JSA only design <br> $\dagger \dagger$ Special models av | d to switch 115 VAC, 60 Hz ilable; contact factory for au | se grounded; JS has 20 <br> ary contacts and additio | mp overload capabilites. information. |  |

## BALANCED ARMATURE RELAYS (10-25 Amps)

|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | 9330 | 9274 | 9324 | 9325 | 9339 |
| Rating: | 10 Amps | 15 Amps | 25 Amps | 25 Amps | 25 Amps |
| Contact configuration: | 2 PDT | 4 PDT | 3 PST/NO | 3 PST-CO/NO | 3 PST/NO w/ 2 Amps, 1 PDT |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | MS24149 | MS24568 | MS27418 | MS27706 | MS6106/41 |
| Electrical Data | 9330 | 9274 | 9324 | 9325 | 9339 |
| Contact rating (Amps) | - | - | - | - | - |
| @ 28 VDC | - | - | - | - | - |
| Resistive: | 10 | 10 | $25^{\dagger}$ | 25 ** | 25 |
| Inductive: | 10 | 10 | $15^{\dagger}$ | 15 | 15 |
| Motor: | 6 | 6 | $20^{\dagger}$ | 20 | 20 |
| Lamp: | 2 | 3 | $10^{\dagger}$ | 10 ** | 10 |
| @ $115 \mathrm{VAC}, 400 \mathrm{~Hz}, 3 \varnothing$ |  |  |  |  |  |
| Resistive: | 10 | 15 | $25^{\dagger}$ | 25 ** | 25 |
| Inductive: | 10 | 10 | $25^{\dagger}$ | 25 ** | 25 |
| Motor: | 6 | 8 ** | $20^{\dagger}$ | 20 | 20 |
| Lamp: | 2 | 4 ** | $10^{\dagger}$ | $10^{\dagger \dagger}$ | 10 㧊 |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, 3 \varnothing$ |  |  |  |  |  |
| Resistive: | 6 | 10 | $25^{\dagger}$ | 25 ** | 25 |
| Inductive: | 4 | 6 | $25^{\dagger}$ | 25 ** | 25 |
| Motor: | 3 | 4 | $12^{\dagger}$ | 12 | 12 |
| Lamp: | 1.5 | 2 | $10^{\dagger}$ | 10 ** | 10 |
| Nominal coil voltage(s): | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ |
| Resistance, Ohms $\pm 10 \%$ : | $160 \Omega$ | $92 \Omega$ | $160 \Omega$ | $160 \Omega$ (each coil) | $160 \Omega$ |
| @ $25^{\circ} \mathrm{C}$ for 28 VDC | - | - | - | - | . |
| Operate time, max. (ms) | - | - | - | - | - |
| DC Coil: | 20 | 25 | 20 | 20 | 20 |
| AC Coil: | 20 | 25 | 20 | 20 | 25 |
| Release time, max. (ms) |  |  |  |  |  |
| DC Coil: | 20 | 20 | 10 | 10 | 10 |
| AC Coil: | 50 | 50 | 50 | 50 | 50 |
| Bounce time, max. (ms): | 2 | N/O 3, N/C 5 | 2 | 5 | 2 Aux. 4 |
| Environmental Data | 9330 | 9274 | 9324 | 9325 | 9339 |
| Sinusoidal vibration (g): | $10$ <br> @ 15-1500 Hz | 10 <br> @ 1000-2000 Hz | 10 @ $55-1500 \mathrm{~Hz}$ | 10 $@ 55-1500 \mathrm{~Hz}$ | 10 @ $55-1500 \mathrm{~Hz}$ |
| Shock (g): | 25 | 50 | 50 | 25 | 50 |
| Temperature range | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Mechanical Data | 9330 | 9274 | 9324 | 9325 | 9339 |
| Weight, max. (oz./lbs.): | 7.04 oz. | 12.80 oz . | 10.56 oz . | 22.7 oz . | 7.04 oz . |
| Dimensions, max. (in.): | $2.50 \times 1.625 \times 2.60$ | $2.062 \times 2.062 \times 1.807$ | $1.531 \times 1.531 \times 1.680$ | $3.54 \times 3.00 \times 3.20$ | $1.531 \times 1.531 \times 1.680$ |
| ( $\mathrm{L} \times \mathrm{W} \times \mathrm{H}$ ) | - | - | - | - | - |
| Option(s) available: | Suppressed DC coil | Suppressed DC coil | Suppressed DC coil | Suppressed DC coil | Suppressed DC coil |

* Max. temp. limited to $+85^{\circ} \mathrm{C}$.
** Value exceeds Mil-Spec.
$\dagger 440$ VAC 60 Hz delta rating, 3.5 amp resistive.
$\dagger \dagger 25 \mathrm{amp}$ resistive load transfer rating.
$\ddagger \ddagger$ Aux. ratings 2 amp resistive, lamp inductive, 0.5 amp lamp.
* $1 \mathrm{NO}+1 \mathrm{NC}$ auxiliary contact ${ }^{* *} \pm 20 \% @ 25^{\circ} \mathrm{C}{ }^{\dagger} 2$ PDT auxiliary contact. May be associated with a Hall current sensor

|  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | 9123 | 9213 | 9207 | 9124 |
| Rating: | 25 Amps | 25-100 Amps | 25-100 Amps | 50 Amps |
| Contact configuration: | 3 PST/NO DM | 3 PST/NO, 4 PST/NO 2 P/NO, 2 P/NC DB-DM | 3 PST/NO DM, 2P/NO, 2P/NC DB-DM | 3 PST/NO DB |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | MS27997 |  | DESC Spec 84192 | MS27222 |
| Electrical Data | 9123 | 9213 | 9207 | 9124 |
| Contact rating (Amps) | - | - | - | - |
| @ 28 VDC | - | - | - | - |
| Resistive: | 25 | 25-100 * | 25-100 * | 50 |
| Inductive: | 25 | 25-100 * | 25-100 * | 50 |
| Motor: | 25 | 25-100 * | 25-100 * | 50 |
| Lamp: | - | - | - | - |
| @ 115 VAC, $400 \mathrm{~Hz}, 3 \varnothing$ | - | - | - | - |
| Resistive: | 25 | 25-100 * | 25-100 * | 50 |
| Inductive: | 25 | 25-100 * | 25-100 * | 50 |
| Motor: | 25 | 25-100 * | 25-100 * | 50 |
| Lamp: | . | - | - | . |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, 3 \varnothing$ |  |  |  |  |
| Resistive: | 15 | 50 * | 50 * | 30 |
| Inductive: | 15 | 50 * | 50 * | 30 |
| Motor: | 7 | 50 * | 50 * | 15 |
| Lamp: | . | - | - | . |
| Nominal coil voltage(s): | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ |
| Resistance, Ohms $\pm 10 \%$ : | $50 \Omega$ | $44.5 \Omega$ | $44.5 \Omega$ | $50 \Omega$ |
| @ $25^{\circ} \mathrm{C}$ for 28 VDC | - | - | - | - |
| Operate time, max. (ms) | - | - | - | - |
| DC Coil: | 25 | 30 | 30 | 25 |
| AC Coil: | 30 | 40 | 40 | 30 |
| Release time, max. (ms) | -- | - | - | - |
| DC Coil: | 10 | 20 | 20 | 10 |
| AC Coil: | 50 | 60 | 50 | 50 |
| Bounce time, max. (ms): | 2 | 10 | 10 | 2 |
| Environmental Data | 9123 | 9213 | 9207 | 9124 |
| Sinusoidal vibration (g): | 15 $@$ $55-1500 \mathrm{~Hz}$ | 10 $@$ $55-1500 \mathrm{~Hz}$ | 10 $@ 55-1500 \mathrm{~Hz}$ | 15 @ $55-1500 \mathrm{~Hz}$ |
| Shock (g): | 50 | 50 | 50 | 50 |
| Temperature range | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Mechanical Data | 9123 | 9213 | 9207 | 9124 |
| Weight, max. (oz./lbs.): | 20 oz . | 44.8 oz. | 2802. | 20 oz . |
| Dimensions, max. (in.): ( $\mathrm{L} \times \mathrm{W} \times \mathrm{H}$ ) | $3.73 \times 3.305 \times 2.50$ | $4.22 \times 4.23 \times 4.53$ | $3.63 \times 3.62 \times 2.875$ | $3.73 \times 3.305 \times 2.50$ |
| Option(s) available: | Auxiliary 5 Amp contacts 440 VAC 60 Hz delta rating | Auxiliary 5-25 Amp contacts | Auxiliary 5-25 Amp contacts | Auxiliary 5 Amp contacts 440 VAC 60 Hz delta rating |

* 440 VAC 60 Hz wye/delta rated. Sealed rotary, 1, 2, 3 and 4 pole.
* 1NO + 1NC auxiliary contact
${ }^{* *} \pm 20 \% @ 25^{\circ} \mathrm{C}{ }^{\dagger}$ 2PDT auxiliary contact. May be associated with a Hall current sensor


## POWER CONTACTORS (50-400 Amps)

|  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Rating: | 50 Amps | 50-400 Amps | 60 Amps | 60 Amps |
| Contact configuration: | $\begin{gathered} 3 \text { PST-NO } \\ 1 \text { PST-NO DM } \end{gathered}$ | 1 PST/NO | 3 PST, 3 PDT, 1 PDT-DB-DM | 3 PST, 3 PDT, 1 PDT-DB-DM |
| Style: |  |  | Magnetic latch | Magnetic latch |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | MS27750 | $\begin{gathered} \text { MS24166 } \\ \text { MS24171/72 } \\ \text { MS24178/79 } \\ \text { MS24185 } \end{gathered}$ | $\begin{gathered} \text { MS27751 } \\ \text { M6106/26 and } 43 \end{gathered}$ | MS27749 |
| Electrical Data | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Contact rating (Amps) | - | - | - | - |
| @ 28 VDC | - | - | - | - |
| Resistive: | 25 | 50-400 | 50 | 50 |
| Inductive: | 15 | 50-100 | 20 | 20 |
| Motor: | 15 | 50-400 | 20 | 20 |
| Lamp: | 10 | - | 10 | 10 |
| @ $115 \mathrm{VAC}, 400 \mathrm{~Hz}, 3 \varnothing$ |  | - |  | - |
| Resistive: | 50 | - | 60 | 60 |
| Inductive: | 50 ** | - | 60 | 60 |
| Motor: | 30 | - | 40 | 40 |
| Lamp: | 15 | - | 15 | 15 |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, 3 \varnothing$ |  | - |  | - |
| Resistive: | 30 | - | 30 | 30 |
| Inductive: | 30 | - | 30 | 30 |
| Motor: | 30 | - | 30 | 30 |
| Lamp: | - | - | - | - |
| Nominal coil voltage(s): | $\begin{gathered} \text { 6, 12, } 28 \text { VDC } \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | 28 VDC | $\begin{gathered} 6,12,28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} \text { 6, 12, } 28 \text { VDC } \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ |
| Resistance, Ohms $\pm 10 \%$ @ $25^{\circ} \mathrm{C}$ for 28 VDC : | $\begin{gathered} 6 \mathrm{VDC}, 12 \Omega ; 12 \mathrm{VDC}, 50 \Omega ; \\ 28 \mathrm{VDC}, 200 \Omega \dagger \\ 115 \mathrm{VAC}, .100 \mathrm{Amp} \end{gathered}$ | $6 \mathrm{VDC}, 12 \Omega ; 12 \mathrm{VDC}, 50 \Omega$; | $\begin{gathered} 6 \mathrm{VDC}, 12 \Omega ; 12 \mathrm{VDC}, 50 \Omega ; \\ 28 \mathrm{VDC}, 200 \Omega ; \\ 115 \mathrm{VAC}, .090 \mathrm{Amp} \end{gathered}$ | $\begin{gathered} 6 \mathrm{VDC}, 12 \Omega ; 12 \mathrm{VDC}, 50 \Omega ; \\ 28 \mathrm{VDC}, 200 \Omega \end{gathered}$ |
| Operate time, max. (ms) | - | - | - | - |
| DC Coil: | 35 |  | 50 | 35 |
| AC Coil: | 35 | 40 | 50 | 35 |
| Release time, max. (ms) |  | - | - | - |
| DC Coil: | 25 | - | 25 | - |
| AC Coil: | 80 | 15 | 80 | - |
| Bounce time, max. (ms): | 3 | - | 3 | 3 |
| Environmental Data | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Sinusoidal vibration (g): | 10 @ 70-1000 Hz | 2 @ 55-500 Hz | 10 @ 70-1000 Hz | 10 @ 70-1000 Hz |
| Shock (g): | 50 | 25 | 50 | 50 |
| Temperature range | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ |
| Mechanical Data | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Weight, max. (oz./lbs.): | 15 oz . | . $59-2.6 \mathrm{lbs}$. | $14 \mathrm{oz} .$ | 1502. |
| Dimensions, max. (in.): $\text { (LxW } \times \mathrm{H})$ | $\begin{gathered} 2.50 \text { diameter } \times 3.13 \\ 4.41 \times 2.0 \times 3.75 \end{gathered}$ | $2.76 \times 2.1 \times 2.56$ | 2.50 diameter $\times 3.13$ | 2.50 diameter $\times 3.13$ |
| Option(s) available: | Gasket sealed models | Special units upon request | Auxiliary 5 Amp contacts | Auxiliary 5 Amp contacts |


|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | 79, 109, 209, 309, 509* 707 | ZC, ZCD Center-off | Z, ZG, ZJ | ZL, ZLD | CCO20 *, CC040 *, CC050 † |
| Rating: | 80-700 Amps | 100 Amps | 120-180 Amps | Up to 120 Amps | 200-400 Amps |
| Contact configuration: | 1 PST/NO DM | 3 PDT-NO, 1 PDT/NO DM-DB | 3 PDT, 3 PST/NO, SPDT-DB-DM | 3 PDT | 1 PST/NO DM |
| Style: | Permanent duty |  | SPST/NO-DM, SPST/NC-DB | 1 PDT-DB-DM (latch) | Permanent duty bus bar mounting |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | AIR 7304 AIR 8456 B |  |  |  | AIR 7304 AIR 8456 B |
| Electrical Data | 79, 109, 209, 309, 509* 707 | ZC, ZCD Center-off | Z, ZG, ZJ | ZL, ZLD | CCO20 *, CCO40 *, CC050 † |
| Contact rating (Amps) | - | - | - | - | - |
| @ 28 VDC | - | - | - | - | - |
| Resistive: | 80-700 | 50 | 50 | 50 | 200-400 |
| Inductive: | 700 | 30 | 30 | 30 | 125-200 |
| Motor: | 40-250 | 30 | 30 | 30 | 125-200 |
| Lamp: | - | - | - | - | - |
| @ $115 \mathrm{VAC}, 400 \mathrm{~Hz}, 3 \varnothing$ | - | - | - | - | - |
| Resistive: | - | 100 | 120-180 | 120 | - |
| Inductive: | - | 100 | 120-180 | 120 | - |
| Motor: | - | 60 | 80-120 | 80 | - |
| Lamp: | - | - | . | - | - |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, 3 \varnothing$ | - | - | - | - | - |
| Resistive: | - | 60 | 60 | 60 | - |
| Inductive: | - | 60 | 60 | 60 | - |
| Motor: | - | 40 | 60 | 60 | - |
| Lamp: | - | - | - | - | - |
| Nominal coil voltage(s): | 28 VDC | $\begin{gathered} \text { 6, 12, } 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} \text { 6, 12, } 28 \text { VDC } \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} \text { 6, 12, } 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | 28 VDC |
| Resistance, Ohms $\pm 10 \%$ <br> @ $25^{\circ} \mathrm{C}$ for 28 VDC : | $\begin{aligned} & \text { 7.2/280 to } \\ & 5 / 200 \end{aligned}$ | $\begin{aligned} & 6 \mathrm{VDC}, 9.3 \Omega ; 12 \mathrm{VDC}, 38 \Omega ; \\ & 28 \mathrm{VDC}, 150 \Omega \text { **; } \\ & 115 \mathrm{VAC}, 0.9 \mathrm{Amp} \end{aligned}$ | $\begin{gathered} 6 \mathrm{VDC}, 7 \Omega ; 12 \mathrm{VDC}, 28 \Omega ; \\ 28 \mathrm{VDC}, 113 \Omega ; \\ 115 \mathrm{VAC}, .12 \mathrm{Amp} \end{gathered}$ | $\begin{gathered} 6 \text { VDC, } 10 \Omega ; 12 \text { VDC, } 40 \Omega ; \\ 28 \text { VDC, } 163 \Omega \text { ** } \end{gathered}$ | 7.2/200, 4.4/152 |
| Operate time, max. (ms) | - | - | - | - | - |
| DC Coil: | 30 | 60 | 60 | 60 | 30 |
| AC Coil: | - | 60 | 60 | 60 | . |
| Release time, max. (ms) | - | - | - | - | - |
| DC Coil: | 20 | 40 | 40 | - | 20 |
| AC Coil: | - | 80 | 40 | - | - |
| Bounce time, max. (ms): | - | 4 | 4 | 4 | - |
| Environmental Data | $79,109,209,309,509 * 707$ | ZC, ZCD Center-off | Z, ZG, ZJ | ZL, ZLD | CCO20 *, CC040 *, CC050 † |
| Sinusoidal vibration (g): | 10 $@ 5-2000 \mathrm{~Hz}$ | @ 70-500 Hz | 10 <br> @ 70-1000 Hz | $\begin{gathered} 10 \\ @ 55-500 \mathrm{~Hz} \end{gathered}$ | 10 @ 5-2000 Hz |
| Shock (g): | 30 | 15 | 50 | 15 | 30 |
| Temperature range | - | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | - |
| Mechanical Data | 79, 109, 209, 309, 509* 707 | ZC, ZCD Center-off | Z, ZG, ZJ | ZL, ZLD | CCO20 *, CC040 *, CC050 † |
| Weight, max. (oz./lbs.): | 7.2-38 oz. | 32-43.2 oz. | 32-43.2 oz. | 2.0-2.75 lbs. | 9 oz . |
| Dimensions, max. (in.): $\text { (L } \times \mathrm{W} \times \mathrm{H})$ | $\begin{gathered} 3.26 \times 1.9 \times 1.42 \text { to } \\ 4.76 \times 2.75 \times 2.46 \end{gathered}$ | 3.65 diameter $\times 4.28$ | 3.65 diameter $\times 4.28$ | 3.65 diameter $\times 4.28$ | $3.1 \times 1.42 \times 3.13$ |
| Option(s) available: | Auxiliary 5 Amp contacts Dust poor enclosure | Gasket sealed models Magnetically latched models | Auxiliary 5 Amp contacts, GFI (Z) Gasket sealed models | Auxiliary 5 Amp contacts | Auxiliary 2 Amp contacts Low level contacts Dust proof enclosure |

*1NO +1 NC auxiliary contact ${ }^{* *} \pm 20 \% @ 25^{\circ} \mathrm{C} \dagger 2$ PDT auxiliary contact. May be associated with a Hall current sensor

|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | W, WC, WL | A, AJ | Busbar Series - HB, ZB, WB | Plug-in Series | Modcon Series |
| Rating: | 250-275 Amps | 300-400 Amps | 60-275 Amps | 60 Amps | 50, 90, 175, 350*** Amps |
| Contact configuration: | 1 PDT-DM-DB, 3 PST/NO 1 PST/NO-DM, 1 PST/NC-DB | 1 PST/NO DM | 3 PST/NO | 3 PST/NO | 3 PST/NO |
| Style: | Non-latch, latch | Non-latch | Non-latch | Non-latch | Non-latch |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | - | M6106/33 | - | - | - |
| Electrical Data | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Contact rating (Amps) | - | - | - | - | - |
| @ 28 VDC | - | - | - | - | - |
| Resistive: | 125 | 300/400 | - | - | - |
| Inductive: | 75 | 100/150 | - | - | - |
| Motor: | 75 | 250/250 | - | - | - |
| Lamp: | - | . | - | - | - |
| @ $115 \mathrm{VAC}, 400 \mathrm{~Hz}, 3 \varnothing$ | - | - | - | - | - |
| Resistive: | 275 | - | 50 to 275 | 60 | 50 to 90 |
| Inductive: | 275 | - | 50 to 275 | - | . |
| Motor: | 175 | - | - | - | - |
| Lamp: | - | - | - | - | - |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, \Delta$ | - | - | - | - | - |
| Resistive: | - | - | - | - | - |
| Inductive: | - | - | - | - | - |
| Motor: | - | - | - | - | - |
| Lamp: | - | - | - | - | - |
| Nominal coil voltage(s): | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \text { (W/WC) } \\ 28 \mathrm{VDC} \text { Suppressed (W/WC) } \end{gathered}$ | 6, 12, 28 VDC | 28 VDC | 28 VDC | 28 VDC |
| Resistance, Ohms $\pm 10 \%$ <br> @ $25^{\circ} \mathrm{C}$ for 28 VDC : | (W) $90 \Omega$; (WL) $9.8 \Omega$ (WC) $100 \Omega^{*}$ | $\begin{gathered} 6 \text { VDC, } 4 \Omega ; 12 \mathrm{VDC}, 15 \Omega ; \\ 28 \mathrm{VDC}, 60 \Omega \end{gathered}$ | - | - | - |
| Operate time, max. (ms) | - | - | - | - | - |
| DC Coil: | 60 | 35 | 12 to 30 | 50 | up to 10 |
| AC Coil: | 60 | - | - | - | - |
| Release time, max. (ms) | - | - | - | - | - |
| DC Coil: | 40 | 15 | 10 to 15 | 20 | up to 10 |
| AC Coil: | 125 | - | - | - | - |
| Bounce time, max. (ms): | 4 | 4 | 4 | 3 | 2 |
| Environmental Data | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Sinusoidal vibration (g): | 10 @ 60-2000 Hz | $\begin{aligned} & 10 @ 70-500 \mathrm{~Hz} \\ & 5 @ 500-2000 \mathrm{~Hz} \end{aligned}$ | $\begin{gathered} 10 @ \\ 5-2000 \mathrm{~Hz} \end{gathered}$ | $\ddagger \ddagger \ddagger \ddagger$ | 执 |
| Shock (g): | 20 | 25 | 20 | 30 | 15 |
| Temperature range | $-55^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-54^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $-15^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Mechanical Data | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Weight, max. (oz./lbs.): | 4.5 lbs . | 1.75 lbs . | Up to 2.01bs | Up to 4.37 lbs . | Up to 0.71 lbs . |
| Dimensions, max. (in.): (L x W x H) | $4.625 \times 5.56 \times 4.10$ | $3.90 \times 3.64 \times 2.80$ | $\begin{aligned} & \text { 4.50in } \times 3.67 \mathrm{in} \times 2.94 \mathrm{in} \\ & \operatorname{Max} \end{aligned}$ | $\begin{gathered} 4.43 \times 4.43 \times 5.0 \\ \operatorname{Max} \end{gathered}$ | $\begin{gathered} 3.51 \times 2.46 \times 2.36 \\ \operatorname{Max} \end{gathered}$ |
| Option(s) available: | Auxiliary 8 Amp contacts Magnetic latch ** Center-off versions $\dagger$, GFI (W) | Auxiliary 5 Amp contacts | Auxiliary 2 Amp contact Dust proof enclosure Gasket Sealed | Auxiliary 5 Amp contacts Smart electronics Dust proof enclosure Gasket Sealed | Dust proof enclosure Gasket Sealed |

[^0]
## SPECIFYING A FIXED TIME DELAY PERIOD

Esterline Power Systems - Leach International and the military identify the time delay period in the same manner. A four-digit dash number specifies the delay period in milliseconds. The first three numbers are significant figures while the fourth indicates the number of zeros to follow the first three.

$$
\begin{aligned}
& \text { Examples: }-1001=1,000 \text { milliseconds }(1 \text { second }) \\
&-2502=25,000 \text { milliseconds }(25 \text { seconds }) \\
&-5000=500 \text { milliseconds }(0.5 \text { second })
\end{aligned}
$$

In the case of a repeat cycle timer (flasher), a similar method is used. The dash number indicates length of each cycle. (Note: each cycle is $50 \%$ on, $50 \%$ off).

$$
\text { Examples: } \begin{aligned}
-2500 & =250 \text { milliseconds cycle or } 4 \text { cycles } / \mathrm{sec} \\
-1001 & =1,000 \text { milliseconds cycle or } 1 \text { cycle } / \mathrm{sec} \\
-6002 & =60,000 \text { milliseconds cycle or } 1 \mathrm{cycle} / \mathrm{min}
\end{aligned}
$$

## USE AND SELECTION OF ADJUSTABLE TIMERS

Adjustable timers are useful in system prototyping or breadboard circuits where the precise time delay period is unknown. By the use of an external resistor, these devices are adjustable over a specific "decade range." Although any decade range within the overall timing range can be supplied, the following ranges are offered as standards:

$$
\begin{aligned}
& 0.1 \text { to } 1 \text { second (Specify }-1001 \text { ) } \\
& 1.0 \text { to } 10 \text { seconds (Specify }-1002 \text { ) } \\
& 5 \text { to } 50 \text { seconds (Specify }-5002 \text { ) } \\
& 50 \text { to } 500 \text { seconds (Specify }-5003 \text { ) }
\end{aligned}
$$

Note from above that in specifying a decade range, the four-digit dash number indicates the high or upper limit of the desired decade range. The formula below provides the proper resistance value to achieve the desired time delay:

$$
\mathbf{R}_{\mathrm{ext}}=\left(\frac{\mathrm{T}_{1}}{\mathrm{~T}_{0}}-1\right) \quad 100,000 \text { Ohms } \quad \begin{array}{r}
\text { Where: } \\
\mathbf{R}_{\text {ext }}=\text { External resistance value (Ohms) } \\
\mathrm{T}_{1}=\text { Desired time in seconds } \\
\mathrm{T}_{0}=\text { Minimum time (low end of the decade range) in seconds }
\end{array}
$$

For example, if a 30 -second delay is desired and a 5 - to 50 -second adjustable timer is being used, the calculation is:

Recommended resistors IAW MIL-R-55182 1⁄8 WATT, 1\% (RNC6OHXXXXFS).

## MILITARY PART NUMBERING METHOD

| M83726 / | XX | XXXX | $\underline{X}$ |
| :---: | :---: | :---: | :---: |
| 1. Basic military specification |  |  |  |
| 2. Specific "slash sheet" |  |  |  |
| 3. Time range designation (see tables above) |  |  |  |
| 4. Terminal and/or quality level designator |  |  |  |


| Military Part Number | Leach Part Number | Operation Mode | Output | Time Range (seconds) |
| :---: | :---: | :---: | :---: | :---: |
| M83726/20 | TD-1435 | Delay on operate - fixed time | 250MA, SPST | 0.05-500 |
| M83726/21 | TD-1436 | Delay on operate - adjustable** | 250MA, SPST | 0.05-500 |
| M83726/22 | TD-1412 | Repeat cycle timer (flasher) | 250MA, SPST | 1-600 cycles/min. ${ }^{\dagger} \dagger$ |
| M83726/23 | TD-1505 | "True" delay on release - fixed $\dagger$ | 10A, 4PDT | 0.1-75 |
| M83726/24 | TDH-1609 | Delay on operate - fixed time | 150MA, SPST | 0.05-500 |
| M83726/25 | TDH-1610 | Delay on release - fixed time | 150MA, SPST | 0.05-500 |
| M83726/28 | TDH-8050/8051 | Delay on operate - fixed time | 10A, 2PDT | 0.1-600 $\ddagger$ |
| M83726/29 | TDH-8070/8071 | Delay on release - fixed time | 10A, 2PDT | 0.1-600 $\ddagger$ |
| M83726/30 | TDH-8060/8061 | Delay on operate - adjustable | 10A, 2PDT | 0.1-600 $\ddagger$ |
| M83726/31 | TDH-8080/8081 | Delay on release - adjustable | 10A, 2PDT | 0.1-600 $\ddagger$ |

[^1]|  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | TDH-6000 | TDH-8000 | TDH-7000 | T531 |
| On operate, fixed time: | TDH-6050/51 | TDH-8050/51 | TDH-7050/51 | T531 |
| On operate, adjustable: | TDH-6060/61 | TDH-8060/61 | TDH-7060/61 | T531 |
| On release, fixed time: | TDH-6070/71 | TDH-8070/71 | TDH-7070/71 | T531 |
| On release, adjustable: | - | TDH-8080/81 | - | T531 |
| Repeat cycle timer (flasher): | - | - | - | - |
| Designed to: | - | MIL-PRF-83726 | MIL-PRF-83726 | - |
| Qualified to: | - | M83726/28, 29, 30, 31 | - | - |
| Electrical Data | TDH-6000 | TDH-8000 | TDH-7000 | T531 |
| Contact rating (resistive): | 10 Amps | 10 Amps | 10 Amps | 25 Amps |
| Contact form: | 2 PDT | 2 PDT | 4 PDT | 3 PDT |
| Timing range (seconds): | 0.1-600 | 0.1-600 | 0.1-600 | 0.1-1000 |
| Accuracy (percentage) *: | $\pm 10$ | $\pm 10$ | $\pm 10$ | $\pm 3$ to $\pm 10$ |
| Recycle time, max. (ms)**: | $50$ | $50$ | 50 | $\leq 50$ |
| Input \& control voltage: | 20-30 VDC | 20-30 VDC | 20-30 VDC | 18-32 VDC |
| Operating current, max.: | 150 mAmps | 150 mAmps | 150 mAmps | - |
| Control current, max.: | - | - | - | - |
| EMI per MIL-STD-461 $\dagger$ : | Class 1D | Class 1D | Class 1D | - |
| Dielectric strength, Vrms | - | - | - | - |
| Sea level: | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $500 / 50 \mathrm{~Hz}$ |
| 80,000 ft.: | $350 / 60 \mathrm{~Hz}$ | $350 / 60 \mathrm{~Hz}$ | $350 / 60 \mathrm{~Hz}$ | 250/50 Hz |
| Insulation resistance megohms: | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | $\geq 500$ @ 500 VDC |
| Environmental Data | TDH-6000 | TDH-8000 | TDH-7000 | T531 |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ): | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 |
| Vibration | - | - | - | - |
| Sine (G): | 20 | 30 | 20 | 20/10-2000 Hz |
| Random ( $\mathrm{G}^{2} / \mathrm{Hz}$ ): | 0.2 | 0.4 | 0.2 | - |
| Shock (g): | 100 | 100 | 100 | $100 / 6 \mathrm{~ms}$ |
| Acceleration (g): | 20 | 15 | 20 | - |
| Seal: | Hermetic | Hermetic | Hermetic | Hermetic |
| Mechanical Data | TDH-6000 | TDH-8000 | TDH-7000 | T531 |
| Weight, max. (oz./lbs.): | $1.9 \mathrm{oz} .(54 \mathrm{~g}$. | $2.5 \mathrm{oz} .(71 \mathrm{~g}$. | 3.0 oz. (85 g.) | 4.233 OZ. (120 g.) |
| $\begin{aligned} & \text { Dimensions, max. (in.): } \\ & (L \times W \times H) \end{aligned}$ | $1.025 \times 5.25 \times 1.520$ | $1.025 \times 1.025 \times 1.010$ | $1.025 \times 1.025 \times 1.50$ | $1.73 \times 1.54 \times 1.02$ |
| Mating socket $\mathrm{P} / \mathrm{N}$ : | SO-1055-8693 | SO-1043-8308 | SO-1056-8691 | S502, SF502 |
| Terminal types $\dagger \dagger$ : | $\begin{aligned} & \text { TDH-60X0=PI } \\ & \text { TDH-60X1=SH } \end{aligned}$ | $\begin{aligned} & \text { TDH-80X0=PI } \\ & \text { TDH-80X1=SH } \end{aligned}$ | $\begin{aligned} & \text { TDH-70X0=PI } \\ & \text { TDH-70X1=SH } \end{aligned}$ | PI, SH |

* The accuracy specification applies to any combination of temperature and voltage. For units with a timing range less than 1 second, add $\pm 10$ milliseconds to the $\pm 10 \%$ tolerance.
** Recycle time is that action which must occur to assure a new timing cycle can be completed within tolerance:
A. TD on operate-Remove power from input terminals for the period specified.
B. TD on release-Apply power to the control terminal for the period specified.
C. "True" TD on release-Apply power to the input terminals for the period specified.
$\dagger$ EMI test limits will not be exceeded during the timing interval or when continuously energized under steady state conditions, per paragraph 3.23, ML-PRF-83726A.
${ }^{\dagger \dagger}$ Definition of terminal type codes:
PI = Plug-in type for use with mating relay socket.
SH = Tinned solder hook terminals for direct hard wiring.
$\mathrm{PC}=$ Tinned straight pins for printed circuit board insertion.
TM = Compatible with M12883/52 socket module and M12883/53 mounting track.
$\ddagger$ Terminals X1 and X2 must be connected together during the test. Dielectric withstanding voltage and insulation resistance are measured between all mutually insulated terminals and between all terminals and case.
${ }^{\ddagger \ddagger}$ Not available for new design; commercially available.

|  |  |  |  | Programmable |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412ł† $\ddagger$ | FLSH402 |
| On operate, fixed time: | TDH-1609 | TD-1435 | - | FLSH402 |
| On operate, adjustable: | - | TD-1436 | - | FLSH402 |
| On release, fixed time: | TDH-1610 | - | - | FLSH402 |
| On release, adjustable: | - | - | - | FLSH402 |
| Repeat cycle timer (flasher): | - | - | TD-1412 | FLSH402 |
| Designed to: | MIL-PRF-83726 | MIL-PRF-83726 | MIL-PRF-83726 | - |
| Qualified to: | M83726/24, 25 | M83726/20, 21 | M83726/22 | - |
| Electrical Data | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412 | FLSH402 |
| Contact rating (resistive): | 150 mAmps | 250 mAmps | 250 mAmps $\ddagger \ddagger$ | 250 mAmps |
| Contact form: | SPST | SPST | SPST | 2 SSO |
| Timing range (seconds): | 0.05-500 | 0.05-500 | 1 cycle/min. to 10 cycles/second | 0.1-625 |
| Accuracy (percentage) *: | $\pm 10$ | $\pm 10$ | $\pm 10$ | $\pm 3$ to $\pm 10$ |
| Recycle time, max. (ms) **: | 10 | 10 | 10 | $\leq 20$ |
| Input \& control voltage: | 20-32 VDC | 18-32 VDC | 18-32 VDC | 18-32 VDC |
| Operating current, max.: | 10 mAmps | $5 \mathrm{mAmps}+$ load | $5 \mathrm{mAmps}+$ load | - |
| Control current, max.: | - | - | - | $5 \mathrm{mAmps} @ 28 \mathrm{VDC}$ |
| EMI per MIL-STD-461 † | Class 1D | Class 1D | Class 1D | - |
| Dielectric strength, Vrms | - | - | - | - |
| Sea level: | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $750 / 50 \mathrm{~Hz}$ |
| 80,000 ft.: | - | $350 / 60 \mathrm{~Hz}$ | $350 / 60 \mathrm{~Hz}$ | - |
| Insulation resistance megohms: | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | $\geq 100$ @ 100 VDC |
| Environmental Data | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412 | FLSH402 |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ): | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 |
| Vibration | - | - | - | - |
| Sine (G): | 20 | 30 | 30 | $30 / 70-2000 \mathrm{~Hz}$ |
| Random ( $\mathrm{G}^{2} / \mathrm{Hz}$ ): | - | - | - | - |
| Shock (g): | 1100 | 1100 | 1100 | 50/11 ms |
| Acceleration (g): | 100 | 100 | 100 | - |
| Seal: | Hermetic | Hermetic | Hermetic | Hermetic |
| Mechanical Data | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412 | FLSH402 |
| Weight, max. (oz.Ilbs.): | . 56 oz. (16g.) | 0.5 oz. (14 g.) | 0.5 oz. (14 g.) | 0.353 oz . (10 g.) |
| Dimensions, max. (in.): (LxWxH) | . $810 \times .410 \times .640$ | . $810 \times .410 \times .310$ | . $810 \times .410 \times .310$ | $0.91 \times 0.91 \times 0.24$ |
| Mating socket P/N: | See note $\dagger \dagger$ | - | - | - |
| Terminal types $t \dagger$ : | TM | SH, PC | SH, PC | PI |

* The accuracy specification applies to any combination of temperature and voltage. For units with a timing range less than 1 second, add $\pm 10$ milliseconds to the $\pm 10 \%$ tolerance.
** Recycle time is that action which must occur to assure a new timing cycle can be completed within tolerance:
A. TD on operate-Remove power from input terminals for the period specified.
B. TD on release-Apply power to the control terminal for the period specified.
C. "True" TD on release-Apply power to the input terminals for the period specified.
$\dagger$ EMI test limits will not be exceeded during the timing interval or when continuously energized under steady state conditions, per paragraph 3.23, MLL-PRF-83726A.
$\dagger \dagger$ Definition of terminal type codes:
PI = Plug-in type for use with mating relay socket.
SH = Tinned solder hook terminals for direct hard wiring.
PC $=$ Tinned straight pins for printed circuit board insertion.
TM = Compatible with M12883/52 socket module and M12883/53 mounting track.
$\ddagger$ Terminals X 1 and X 2 must be connected together during the test. Dielectric withstanding voltage and insulation resistance are measured between all mutually insulated terminals and between all terminals and case.
$\ddagger \ddagger$ Output rating equivalent of two MS25237-387 IAmps in parallel.
$\ddagger \ddagger \ddagger$ Not available for new design; commercially available.

|  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Description: | AC Power Monitor | DC Voltage Sensor | AC Under or Over Voltage Sensor | Frequency Sensor | Phase Sequence Sensor | Current Sensing Relay |
| Operational Data | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Input Supply: | $\begin{gathered} 90-150 \text { VRMS } \\ \text { 180-240 VRMS } \\ 44-450 \mathrm{~Hz} \\ 3 \varnothing, 4 \text { wire } \end{gathered}$ | 19.5-30 VDC | $\begin{gathered} 90-150 \text { VRMS } \\ \text { 180-240 VRMS } \\ 50-450 \mathrm{~Hz} \\ 3 \varnothing, 4 \text { wire } \end{gathered}$ | $\begin{gathered} 80-150 \text { VRMS } \\ \text { 160-240 VRMS } \\ 40-480 \mathrm{~Hz} \\ 3 \varnothing, 4 \text { wire } \end{gathered}$ | $\begin{gathered} 90-150 \text { VRMS } \\ \text { 180-240 VRMS } \\ 44-450 \mathrm{~Hz} \\ 3 \varnothing, 4 \text { wire } \end{gathered}$ | 18-32 VDC |
| Sensed voltage: | - | 1-50 VDC | - | - | - | - |
| Sensing Functions: | Trip point ranges Under voltage: <br> 90-130 VRMS, $\pm 2 \%$ 180-220 VRMS, $\pm 2 \%$ <br> Over voltage: <br> $110-150$ VRMS, $\pm 2 \%$ <br> 200-240 VRMS, $\pm 2 \%$ <br> Under frequency: $44-58 \mathrm{~Hz}, \pm 2 \%$ $350-390 \mathrm{~Hz}, \pm 2 \%$ <br> Over frequency: <br> $55-62 \mathrm{~Hz}, \pm 2 \%$ <br> $410-450 \mathrm{~Hz}, \pm 2 \%$ <br> Phase rotation ABC <br> Time delay: <br> $.05-10$ sec., $\pm 10 \%$ | Energize above, de-energize below selected trip point: $1-50$ VDC, $\pm 2 \%$ | Selected trip point within: 90-130 VRMS or $180-230$ VRMS, $\pm 2 \%$ | Energize above, de-energize below selected trip point: $320-480 \mathrm{~Hz}, \pm 2 \%$ Senses any one line to neutral | Energize when phase sequence is ABC . De-energize for all other sequences, open neutral or loss of voltage | Sensing range: 0.8-49 Amps Min. pickup: <br> Max. pickup: 5.5-49 Amps Min. dropout: 0.08-8 Amps Min. delta: 0.16-1.6 Amps Max. delta: 4-31 Amps |
| Output contacts: * | 2 PDT, 10 Amps or 3 PDT, 10 Amps | 10 Amps 2 PDT or 4 PDT | 10 Amps 2 PDT or 4 PDT | 10 Amps 2 PDT or 4 PDT | 10 Amps 2 PDT or 4 PDT | 2 Amps <br> 2 PDT |
| Environmental Data | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ): | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 |
| Thermal shock (MIL-STD-202): | Method 107 | Method 107 | Method 107 | Method 107 | Method 107 | - |
| Vibration (MIL-STD-202): | Method 204 ** | Method 204 ** | Method 204 ** | Method 204 ** | Method 204 ** | $15 \mathrm{~g} .170-3000 \mathrm{~Hz}$ |
| Random: | Method 214 † | Method $214 \dagger$ | Method $214 \dagger$ | Method 214 † | Method $214 \dagger$ | - |
| Shock (MIL-STD-202): | Method $213 \dagger \dagger$ | Method $213 \dagger \dagger$ | Method $213 \dagger \dagger$ | Method $213 \dagger \dagger$ | Method $213 \dagger \dagger$ | 50G/11 ms |
| Acceleration (MIL-STD-202): | Method 212 | Method 212 | Method 212 | Method 212 | Method 212 | - |
| Seal: | Hermetic (potted) | Potted | Potted | Potted | Potted | Hermetic |
| Mechanical Data | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Weight, max. (oz./grams): | 27 oz. (767 g.) | $10 \mathrm{oz}$. (284 g.) | $10 \mathrm{oz}$. (284 g.) | $10 \mathrm{oz}$. (284 g.) | $10 \mathrm{oz}$. (284 g.) | 2.469 oz . (70 g.) |
| Dimensions, max. (in.): (L x W x H) | $2.31 \times 2.18 \times 3.2 \ddagger$ | $1.531 \times 1.531 \times 2.34$ | $1.531 \times 1.531 \times 2.34$ | $1.531 \times 1.531 \times 2.34$ | $1.531 \times 1.531 \times 2.34$ | $1.73 \times 1.01 \times 1.02$ |
| Finish: | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type 1 ¢ $\ddagger$ | Corrosion resistant |
| Engineering Data | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Insulation resistance: | 100 M Ohms | 100 M Ohms * | 100 M Ohms | 100 M Ohms | 100 M Ohms | >100 M Ohms @ 50VDC |
| Dielectric strength (MIL-STD-202): | Method 301 | Method 301 | Method 301 | Method 301 | Method 301 | 1000 VRMS/50 Hz. |
| Voltage strength <br> (MIL-STD-202): | Method 301 | Method 301 | Method 301 | Method 301 | Method 301 | - |
| Voltage transients (MIL-STD-704): | Category B | Category B | Category B | Category B | Category B | - |
| Operating current |  |  |  |  |  | - |
| AC sensors, max. (mAmps): | 75 per phase | 75 per phase | 75 per phase | 75 per phase | 75 per phase | - |
| DC sensors, max. (mAmps): | 175 | 175 | 175 | 175 | 175 | - |
| EMI (MIL-STD-461): | Class 1D | Class 1D | Class 1D | Class 1D | Class 1D | - |
| Life test | - | - | - | - | - | - |
| High level (cycles, min.): | 100,000 | 100,000 | 100,000 | 100,000 | 100,000 | - |
| Low level (cycles, min.): | 100,000 | 100,000 ** | 100,000 | 100,000 ** | 100,000 * | - |

## SOLID STATE POWER CONTROLLERS

|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | P110 | P140 | P150 | P600-Air | P800 |
| Rating: | 2 Amps | 1, 2, 4, 5, 7.5 and 10 Amps | $\begin{gathered} 2,7,10,15,20,25 \\ \text { and } 30 \text { Amps } \end{gathered}$ | 80 Amps | 150 Amps |
| Style/Voltage: | PCB Mounted/28 VDC | PCB Mounted/28 VDC | PCB Mounted/28 VDC | Stand Alone/28 VDC | Stand Alone/28VDC |
| Designed to: | MIL-P-81653** | MIL-P-81653** | MIL-P-81653** | MIL-P-81653** | - |
| Electrical Data | P110 | P140 | P150 | P600-Air | P800 |
| Bias on (voltage): | - | 4.5-5.5 or 18-32 | 4.5-5.5 | 4.5-5.5 or 16-33.5 | 16-33.5 |
| Control on (voltage): | 4.5-32 | 2.4-32 | 2.4 min. (TTL) | 16-32 | 16-33.5 |
| Statue Output Type: | - | Load Current, Voltage | Load Current + Trip | Load Current + Trip + RCCB | Gate, LVD + RCCB |
| Typical Operate Time (ms): | 0.15 | 0.1 | 0.2 | 1 | 5 |
| Full Load Voltage Drop (mV): | 150 | 100 | 100 | 100 | 300 |
| Environmental Data | P110 | P140 | P150 | P600-Air | P800 |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ): | $\begin{gathered} -55 \text { to }+110 \\ \text { (Derated from }+105 \text { ) } \end{gathered}$ | -55 to +125* | -55 to $+125^{*}$ <br> (Derated from +105 ) | -40 to +70 | -40 to +71 |
| Vibration (g): | 20 (20-2000 Hz) | 20 (96-2000 Hz) | 20 | $5(5-500 \mathrm{~Hz})$ | 13.3 (10-2000 Hz) |
| Shock (g): | 1500 | 1500 | 1500 | 30 | 6 |
| Acceleration (g): | 5000 | 5000 | 5000 | 10 | 6.75 |
| Seal: | Hermetic | Hermetic | Hermetic | Hermetic | - |
| Mechanical Data | P110 | P140 | P150 | P600-Air | P800 |
| Weight, max. (grams): | 5 | 20 | 65 | 500 | 500 |
| Dimensions, max. (mm): $(\mathrm{L} \times \mathrm{W} \times \mathrm{H})$ | $20.6 \times 10.4 \times 6.35$ | $25.7 \times 25.7 \times 9.5$ | $69.6 \times 34 \times 9.7$ | $95 \times 84.5 \times 75$ | $80 \times 96 \times 45$ |



| Leach Series: | EPM-109 | EPM-110 | EPM-111 | EPM-112 (WHCU) |
| :---: | :---: | :---: | :---: | :---: |
| Rating: | 7.5 and 12 Amps | 40 Amps | 60 Amps | 40 Amps (Dual Channel) |
| Style/Voltage: |  |  |  | 28 Vdc |
| Designed to: |  |  |  |  |
| Electrical Data | EPM-109 | EPM-110 | EPM-111 | EPM-112 (WHCU) |
| Bias on (voltage): | 4.5-5.5 | 4.5-5.5 | 4.5-5.5 | 28 Vdc |
| Control on (voltage): |  |  |  | Temperature Controlled |
| Statue Output Type: |  |  |  | ARINC 429 |
| Typical Operate Time (ms): |  |  |  |  |
| Full Load Voltage Drop (mV): |  |  |  | 100 mV |
| Environmental Data | EPM-109 | EPM-110 | EPM-111 | EPM-112 (WHCU) |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ): | -40 to +75 | -40 to +75 | -40 to +75 | -40 to +71 |
| Vibration (g): | 20 (20-2000 Hz) | 20 (20-2000 Hz) | 20 (20-2000 Hz) | 4.12 (10-2000 Hz) |
| Shock (g): | 500 | 500 | 500 | 20 |
| Acceleration (g): | 500 | 500 | 500 | 18 |
| Seal: |  |  |  |  |
| Mechanical Data | EPM-109 | EPM-110 | EPM-111 | EPM-112 (WHCU) |
| Weight, max. (grams): | 150 | 150 | 500 | 650 |
| Dimensions, max. (mm): $(\mathrm{L} \times \mathrm{W} \times \mathrm{H})$ | $91 \times 91 \times 23$ | $91 \times 91 \times 23$ | $80 \times 96 \times 41$ | $80 \times 96 \times 62.3$ |

${ }^{*} 1 \mathrm{NO}+1 \mathrm{NC}$ auxiliary contact ${ }^{* *} \pm 20 \% @ 25^{\circ} \mathrm{C} \dagger 2 \mathrm{PDT}$ auxiliary contact. May be associated with a Hall current sensor $\dagger \dagger$ Refer to document RTCA/DO-160

## SPECIAL CATEGORY

Esterline Power Systems offers a comprehensive LEACH ${ }^{\circledR}$ product line and extensive experience in developing component products for electrical systems. Most LEACH ${ }^{\circledR}$ component products feature lightweight, compact, rugged construction, and many are hermetically sealed and qualified to the appropriate military specification. Their use provides our customer with major design advantages coupled with significant cost savings.


## Ground Fault Interrupter Series

Leach Ground Fault Interrupt (GFI) relays sense fuel pump ground faults, while Leach Fault Current Detection (FCD) relays sense fuel pump ground faults and phase-to-phase shorts in the fuel pump and up-stream wiring. Through the use of a proprietary electronic circuit design, Leach GFI and FCD relays detect these faults and open the circuit within milliseconds, thereby minimizing the potential for fuel-system combustion.


## DC Current Sensor Series

The Hall Effect current sensor, with a galvanic insulation, is designed to measure DC current and is fully certified to DO-160. The output provides an accurate linear voltage signal versus measured current and has a full bidirectional scale range.


## Battery Management System

This Battery Control Unit, using Ideal Diode technology (patented), is a battery management system, designed for 28 Vdc lithium-ion batteries. It is specifically designed to meet the requirements of managing and protecting battery packs for both commercial, military aerospace, and ground vehicles.


## AC Smart Module

The AC Smart Module is fit for commercial and military aerospace power distribution systems. It can be used as a remote control circuit breaker when interfaced with an external contactor. It also has a dedicated load monitoring and protection function, and can be paired to provide precision differential protection.


## Solid-State Power Controller (SSPC)

In response to customers' expanding needs, we have developed the next g eneration of Solid-State Power Controllers. This new model will be ideal for a variety of aerospace, military and transportation applications where advanced communications features and a "system friendly" interface are desired. Like Leach's standard SSPCs, these devices will feature a rugged design and a high MTBF.

## Power Management Systems

Esterline Power Systems offers a variety of power distribution configurations from electro-mechanical power management to fully integrated SSPC power management, including control logic and protection. Designed with LEACH ${ }^{\circledR}$ components, these assemblies satisfy all specific customer program conditions and requirements for both primary and secondary distribution systems.


## Features:

- Multi-channel Solid State Power Controllers (SSPCs)
- Microprocessor-based technology
- Solid state switching up to 100 Amps per channel
- Automatic load shedding
- Programmable operating modes and trip curves
- Built-in-test at power-up, during continuous operation, or in manual mode
- CAN J1939, MIL-STD-1553B, ARINC-485, ARINC-429 and Ethernet.


## Benefits:

- Configurable
- IP-67 ready (Waterproof)
- MIL-Spec connectivity
- Optimized heat dissipation
- Small footprint \& lightweight
- Field replaceable
- Electro-mechanical option


## High Reliability Components

The LEACH ${ }^{\circledR}$ name is synonymous with high reliability relays since the first space launch and Leach products are on virtually all major space programs. Today, Esterline Power Systems produces more Leach relays for space applications than all of our competitors combined. Our heritage in aerospace led to the development of our hi-rel product line to support our customer's critical space applications.


KL Series


KCL Series


JL Series

## U.S. PART NUMBERING SYSTEM

Basic series designation

1. Mounting styles (A, $D, E, G, J)$
2. Terminal types $(1,2,4,7)$
3. Coil voltage, see coil characteristics (A, B, C, M, N, R, V) $\qquad$
4. XXX Designators

Example : X-A1A-XXX
X-A1A (Commercial)
X-A1A-300 L,M (MIL)
X-A1A-123 (Customer Part)

## DISTRIBUTION

For a list of authorized distributors please go on our website under the Contact page. www.esterline.com/powersystems/Contact/TheAmericas

## Esterlunç

## Power Systems

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Hong Kong


[^0]:    ${ }^{*} \pm 20 \%$ @ $25^{\circ} \mathrm{C} * * W L$ model ${ }^{* * * A v a i l a b l e ~ i n ~} 2017{ }^{\dagger}$ WC model ${ }^{\dagger \dagger} \mathrm{Z}$ model ${ }^{\ddagger}$ Current sensing with remote control capability ${ }^{\ddagger \ddagger}$ Shor-t-ime rated for starting loads. ${ }^{\ddagger \ddagger \ddagger \ddagger}$ Contact factory for detailed information

[^1]:    ** All adjustable timers use external resistor (not supplied) to adjust timing range.
    $\dagger$ "True" time delay on release requires no external power during timing period.
    $\dagger \dagger$ Each cycle is $50 \%$ on, $50 \%$ off.
    $\ddagger$ Timing ranges above 500 seconds are not MIL qualified.

